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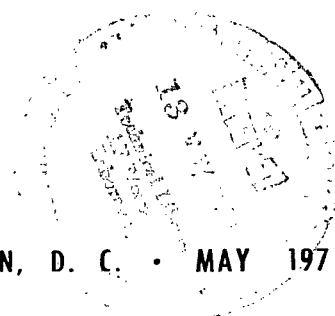
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COMPUTER PROGRAM FOR THERMAL ANALYSIS OF TANK-MOUNTED MULTILAYER INSULATION

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16. Abstract An analysis was done on the space-hold thermal performance of various multilayer insulation configurations on an oblate spheroidal tank. The thermal code CINDA-3G (Chrysler Improved Numerical Differencing Analyzer for Third Generation Computers) was used for the thermal analysis, and several subroutines were written to tailor it for the needs of the problem. A portion of the tailoring is called the pre-preprocessor, which generates the data required as input to CINDA-3G. This pre-preprocessor and allied subroutines comprise a package to obtain a parametric thermal study with a minimum amount of input data. Parameters may be changed with a minimum of effort.		13. Type of Report and Period Covered Technical Note		
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COMPUTER PROGRAM FOR THERMAL ANALYSIS OF TANK-MOUNTED MULTILAYER INSULATION

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SUMMARY

A computer program was developed to analyze the space-hold thermal performance of various multilayer insulation (MLI) configurations on the upper half of an oblate spheroidal liquid-hydrogen tank. The thermal model considered was an unshrouded tank within a hypothetical sun-oriented vehicle such that the payload was the only heat source in the system.

The thermal code CINDA-3G (Chrysler Improved Numerical Differencing Analyzer for Third Generation Computers) was chosen for the basic thermal analysis, and several subroutines were written to tailor it for the needs of the particular problem. A portion of the tailoring included a program called the pre-preprocessor, which generated the data required as input for the CINDA-3G program.

This pre-preprocessor and allied subroutines comprise a package to obtain a parametric thermal analysis of any multilayer covering on a spheroid. As a result, a minimum amount of input is required to specify the model geometry so that perturbations in the geometry configuration may be introduced with a minimum of effort.

INTRODUCTION

The long-term storage of liquid hydrogen in space can be effectively accomplished by using high-performance multilayer insulation (MLI) systems. A typical system would use a large number of highly reflective shields (aluminized polyester film) separated by low-thermal-conductivity spacers (e. g. , silk netting).

A cross-sectional view of a sun-oriented vehicle with an unshrouded liquid-hydrogen tank covered with MLI is shown in figure 1. The payload intercepts all solar energy and thus represents the only high-temperature heat source in the vehicle. The direction of the anticipated heat flows could be as indicated by the arrows in figure 1. The only heat

being transferred into any of the tanks is through the MLI on the top half of the liquid-hydrogen tank. Therefore, this discussion will consider the thermal performance of the MLI on the top half of the liquid-hydrogen tank only.

This analysis will be general for a steady-state study of any oblate spheroidal tank and payload geometry. However, to simplify the discussion, the programs herein will be described with respect to a particular problem; that is, a steady-state analysis of a variable-thickness shield of MLI on the top half of an oblate spheroidal tank viewing a constant-temperature payload. A complete discussion and the results of this problem for the geometries considered may be found in reference 1.

A cross-sectional view of the variable-thickness MLI system on the top half of the liquid-hydrogen tank is shown in figure 2. The net heat flow by thermal radiation into the top surface of the MLI is transferred within the MLI by

- (1) Conduction in the lateral direction parallel to the shields, Q_{lat}
- (2) Combination of radiation and conduction in the normal direction perpendicular to the shields, Q_{norm}

For a steady-state condition to exist, the net thermal radiation received by the top surface of the MLI must be exactly equal to the total heat transferred through the MLI and into the liquid-hydrogen tank. The problem then becomes one of solving for the net heat flows after temperatures resulting from local heat balances throughout the MLI have been established.

There are a number of computer programs available which, when fed the proper input data to describe the model of a physical problem, will perform a thermal analysis and output the temperature distribution. When these programs are used, both building the mathematical model which describes the physical geometry and the preparation of the necessary input data are most tedious. To alleviate this difficulty, the computer subroutines described in this report were written to provide a ready means to generate this input data.

These subroutines are specifically designed to solve the problem described in reference 1, but can be generally applied to any tank in the shape of an oblate spheroid with layers of material covering the tank, or for a shell of varying thickness having the same general shape. These computer programs, then, generate the data required by CINDA-3G (ref. 2), which is the particular thermal analysis program chosen by the authors because of its versatility. The capability to readily effect small changes in geometry added to the versatility and afforded a substantial saving in time and effort.

The routines to be described herein are (1) a pre-preprocessor which takes the input data and converts it to the CINDA-3G data as prescribed by that program, (2) a view factor program which computes the geometric view factors for radiation in an enclosure, (3) an output routine which graphically displays the temperatures, thus making it easier to get an overall view of the temperature distribution, and (4) various other subroutines that are used for special operations by routines (1), (2), and (3).

ANALYSIS

Thermal Model

The thermal model for this problem is shown in figures 3 and 4. It consists of a 45° wedge of the MLI on top of an oblate spheroidal tank. This wedge is divided into a number of internal nodes.

For convenience, the geometry of all the nodes in a given column is assumed to be identical in the normal direction, having numerical values for the node width, node length, the lateral cross-sectional area (ALAT), and the normal area (ANORM) based on the dimensions on the top surface of the MLI. This should introduce no significant error when the maximum MLI thickness is small relative to the minor tank radius.

The node length for each segment (column) is described by specifying the angles $\theta_1, \theta_2, \dots, \theta_n$ (all θ 's must be integers). The depth of all nodes is constant and is specified by two input variables: the number of shields in each node, NSPL, and the thickness of each shield, DELS. The product of NSPL and DELS then is the depth of each internal node. The number of nodes in each column is an input variable, NL, which is a function of the MLI thickness being simulated in that particular column. The program is set up to accept a maximum of 30 segments and up to 50 nodes in each column. For the particular problem under discussion, 10 segments were used with varying numbers of layers (see fig. 3). The computed performance of this wedge is then multiplied by 8 to obtain the results for the entire top half of the tank.

A constant-value boundary node represents the temperature of the tank and the tank surface is held at this constant temperature. The payload is simulated by a flat disk divided into concentric rings (maximum, 10 rings). Space is simulated by a constant-temperature node with temperature at absolute zero and an emissivity equal to unity (blackbody).

Thermal Radiation

An enclosure composed of the payload, the surface of the MLI, and an imaginary surface representing space is used to compute the net thermal radiation received by the top surface of the MLI. The enclosure formed with the various surfaces labeled is shown in figure 5. The enclosure used in this discussion is composed of the 10 tank surface areas, five payload surface areas, and an imaginary surface simulating space, for a total of 16 surfaces.

The payload surface represented by a flat disk is divided into concentric rings of approximately equal area (labeled A_{11} to A_{15} in fig. 5). Each of these rings is consid-

ered to be a separate surface of the enclosure, and as such, each ring may have a different surface emissivity and a different constant temperature which is considered to be an infinite heat source. This is then assumed to be a multiple gray surface enclosure and simulates a radiosity network. A CINDA-3G subroutine, IRRAD1, is then used to compute the net radiant heat flow rates to each surface of the enclosure. Subroutine IRRAD1 uses a method described in reference 3 to obtain the net radiant heat flow to each surface.

Computer Program - General

CINDA-3G is a two-pass or double-phase operation consisting of a preprocessor phase and an execution phase. The user input data (description of the model) to CINDA-3G are converted into FORTRAN IV language subroutines by the preprocessor. These subroutines are then passed onto the system FORTRAN compiler for compilation and execution for solution of the problem.

Since the user input data as described in reference 2 are for a fixed geometric model, much extra labor would be necessary to change the input for a slightly modified geometry. Thus, a set of subroutines were written to accept a general description of the model and to generate the user input data so that the geometry can easily be varied by small changes in input data. This set of author-written subroutines was added to the CINDA-3G system as an additional phase of operation, making a three-pass or three-phase operation. This additional phase, called the pre-preprocessor, is executed first to generate all the necessary input data as required by the CINDA-3G preprocessor using a minimum amount of punched card input data. The CINDA-3G data are described in reference 2 (pp. 4.1 to 4.21). Control is then passed to the CINDA-3G preprocessor (phase 2) to process this generated data and to generate the subroutines for the third phase of the operation to perform the execution of the problem.

Because of this method of combining the three phases of operation and the use of certain portions of the computer operating system, this overall program as described is usable only on IBM 7094 II/7044 Direct Couple Systems running under the operating system IBSYS version 13, with a FORTRAN IV compiler. However, the CINDA-3G program is available for other computer configurations, for example UNIVAC 1108; and the routines written by the authors as described in this report could easily be modified to operate on these other computers since they are entirely written in FORTRAN IV.

Finite Difference Equations

The input to CINDA-3G is the description of the model. This description is given by

designating each incremental volume, called a node, by a number and then describing the heat paths between nodes by specifying the node numbers of the two adjoining nodes and a value which represents the conductance between these two nodes. Conductance is the area of heat flow times the thermal conductivity divided by the conductor length. Heat flow to boundaries is specified by supplying heat-transfer coefficients or radiation constants as the conductance between the two nodes.

When a network (model) to the problem has been described, the solution is obtained by solving a set of finite difference equations, which are an approximation to the partial differential equations of the diffusion type

$$\frac{\partial T}{\partial t} = \alpha \nabla^2 T + S \quad (1)$$

where T is temperature, t is time, α is diffusivity

$$\alpha = \frac{k}{C_p} \quad (2)$$

∇^2 is the Laplacian operator in x, y, z coordinates, and S is a source term defined as

$$S = \frac{\dot{q} \alpha}{k} \quad (3)$$

where \dot{q} is heat rate per unit volume and k is thermal conductivity.

Since we are interested in only the steady-state solution for this particular problem, the time derivative is equal to zero, and equation (1) reduces to Poisson's equation:

$$\alpha \nabla^2 T + S = 0 \quad (4)$$

Substituting equations (2) and (3) into equation (4) results in

$$\frac{k \nabla^2 T}{\rho C_p} + \frac{\dot{q} k}{k \rho C_p} = 0 \quad (5)$$

Then since ρC_p may be assumed to be a constant for steady-state computation, multiply both sides of equation (5) by ρC_p to get

$$k\nabla^2 T + \dot{q} = k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) + \dot{q} = 0 \quad (6)$$

Then

$$k\nabla^2 T + \dot{q} \cong \frac{k}{\Delta x} \left(\frac{\partial T}{\partial x^-} - \frac{\partial T}{\partial x^+} \right) + \frac{k}{\Delta y} \left(\frac{\partial T}{\partial y^-} - \frac{\partial T}{\partial y^+} \right) + \frac{k}{\Delta z} \left(\frac{\partial T}{\partial z^-} - \frac{\partial T}{\partial z^+} \right) + \dot{q} \quad (7)$$

where the plus and minus signs in the first partial term indicate that they are taken on the negative or positive side, respectively, of the point under consideration. If three consecutive points (1, 0, and 2) ascending in the x direction are considered, the finite difference of the x portion of equation (7) is

$$\frac{k}{\Delta x} \left(\frac{\partial T_0}{\partial x^-} - \frac{\partial T_0}{\partial x^+} \right) \cong \frac{k}{\Delta x} \left(\frac{T_1 - T_0}{\Delta x^-} + \frac{T_2 - T_0}{\Delta x^+} \right) \quad (8)$$

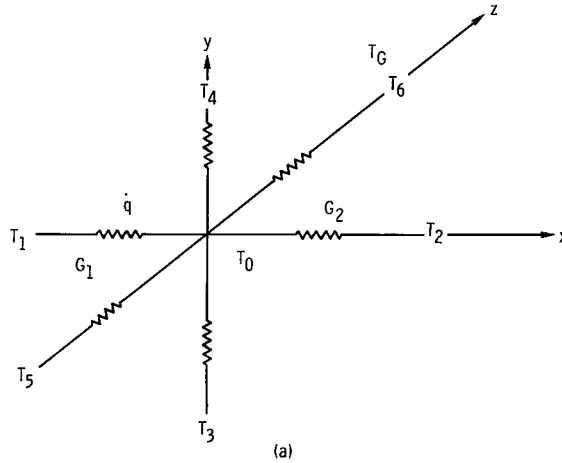
applying this to equation (7) for x , y , and z for the points

1, 0, 2 in x direction

3, 0, 4 in y direction

5, 0, 6 in z direction

yields:



$$k\nabla^2 T_0 + \dot{q} = \frac{k}{\Delta x} \left(\frac{T_1 - T_0}{\Delta x^-} + \frac{T_2 - T_0}{\Delta x^+} \right) + \frac{k}{\Delta y} \left(\frac{T_3 - T_0}{\Delta y^-} + \frac{T_4 - T_0}{\Delta y^+} \right) + \frac{k}{\Delta z} \left(\frac{T_5 - T_0}{\Delta z^-} + \frac{T_6 - T_0}{\Delta z^+} \right) + \dot{q} \quad (9)$$

taking common denominator of volume $V = (\Delta x)(\Delta y)(\Delta z)$ and $A_x = (\Delta y)(\Delta z)$,
 $A_y = (\Delta x)(\Delta z)$, $A_z = (\Delta x)(\Delta y)$ and combining equation (9) with equation (6) to obtain

$$\begin{aligned} \frac{kA_x}{\Delta x^-} (T_1 - T_0) + \frac{kA_x}{\Delta x^+} (T_2 - T_0) + \frac{kA_y}{\Delta y^-} (T_3 - T_0) + \frac{kA_y}{\Delta y^+} (T_4 - T_0) + \frac{kA_z}{\Delta z^-} (T_5 - T_0) \\ + \frac{kA_z}{\Delta z^+} (T_6 - T_0) + \dot{q} = 0 \end{aligned} \quad (10)$$

now let $G_1 = kA_x/\Delta x^-$, $G_2 = kA_x/\Delta x^+$, $G_3 = kA_y/\Delta y^-$, . . . , etc. Then

$$\begin{aligned} G_1 (T_1 - T_0) + G_2 (T_2 - T_0) + G_3 (T_3 - T_0) + G_4 (T_4 - T_0) + G_5 (T_5 - T_0) \\ + G_6 (T_6 - T_0) + \dot{q} = 0 \end{aligned} \quad (11)$$

$$\begin{aligned} G_1 T_1 + G_2 T_2 + G_3 T_3 + G_4 T_4 + G_5 T_5 + G_6 T_6 + \dot{q} \\ = T_0 (G_1 + G_2 + G_3 + G_4 + G_5 + G_6) \end{aligned} \quad (12)$$

or

$$T_0 = \frac{G_1 T_1 + G_2 T_2 + G_3 T_3 + G_4 T_4 + G_5 T_5 + G_6 T_6 + \dot{q}}{G_1 + G_2 + G_3 + G_4 + G_5 + G_6} \quad (13)$$

or, in more general terms,

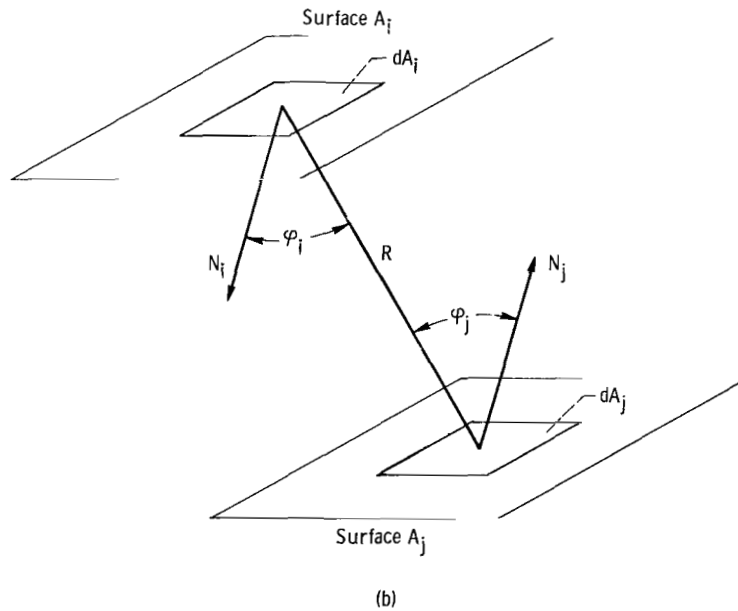
$$T_0 = \frac{\sum G_i T_i + \dot{q}_0}{\sum G_i} \quad (14)$$

where i ranges over all neighboring nodes to T_0 .

Since all the temperatures T_i in equation (14) are not known, assume some initial temperatures and solve this equation for T_0 ; when this is done over all the nodes in the network, a new temperature distribution will be obtained. Iterate in this fashion with equation (14) over all the nodes in the network until the temperatures obtained do not change between two consecutive iterations by more than some prescribed value, called the convergence criterion. This is the method used by the execution routine CINDSS (see ref. 2).

Geometric Radiation View Factors Between Surfaces on a Flat-Surfaced Payload and a Spheroidal Tank

The geometric radiation view factor between any two surfaces A_i and A_j shown in the following sketch is defined by equation (15)



$$A_i F_{i,j} = \int_{A_i} \int_{A_j} \frac{\cos \varphi_i \cos \varphi_j dA_i dA_j}{\pi R^2} \quad (15)$$

where $F_{i,j}$ represents the portion of the total energy, either emitted or reflected by surface i , that is intercepted by surface j . As shown in the sketch, φ_i and φ_j are the angles between the respective normals to the surface elements dA_i and dA_j and the connecting line R .

The double integral in equation (15) is approximated by the following double summation in order to obtain a numerical solution on the digital computer:

$$A_i F_{i,j} = \sum_{A_i} \sum_{A_j} \frac{\cos \varphi_i \cos \varphi_j \Delta A_i \Delta A_j}{\pi R^2} \quad (16)$$

The radiosity subroutine used to calculate the net heat into each surface of the enclosure requires the following numerical input:

- A_{N_E} area of each surface in the enclosure
- T_{N_E} temperature of each surface in the enclosure
- ϵ_{N_E} emissivity of each surface in the enclosure
- $A \times F$ area times geometric view factor for each interchange in the enclosure (see ref. 2, p. 6.6.2)

The procedure described in this section first determines the individual values of $A \times F$ for each of the tank surfaces viewing each of the payload surfaces. Once these primary values are determined, all other values of $A \times F$ are readily determined. The equations used to define the other values of $A \times F$ are discussed at the very end of this section.

The view factors, and subsequently the net q into each of the surfaces in the radiosity enclosure, are computed for the entire top half of the tank and the entire payload. As described earlier, in the discussion of the model, the top node of each column of MLI is a 45° segment. These segments are extended completely around the tank to form a ring and the net q is computed for each of these rings. These q 's are then divided by 8 to obtain the net q into each node on top of the MLI. The method of computing the view factors described herein further breaks up each of these rings on the MLI and also breaks up the payload surfaces, described on page 3, into smaller rings. Then these small areas with their respective view factors are added together to obtain the $A \times F$ for each payload surface and each MLI surface, where each MLI surface is a ring as described previously.

The actual view factors are calculated as follows: The payload is arbitrarily divided into concentric rings each having a width of 0.1 foot (3.05 cm). Each ring with area A_p is then further divided into incremental areas ΔA_p . As shown in figure 6, the subscript p will pertain to the payload surface, and the subscript t will pertain to the tank surface. The number of incremental areas in each ring N_J is varied so that the numerical value of ΔA_p remains approximately constant over the entire payload. Thus, for the payload ring shown in figure 6, N_J is the nearest whole number determined by the following expression:

$$N_J = 20\pi R_p \quad (17)$$

The number of these rings of 0.1-foot (3.05-cm) width which are to be included in each of the individual payload surfaces is then readily determined.

The MLI surface on the tank is arbitrarily divided into 90 increments of 1° each, measured from the vertical z -axis. As shown in figure 6, the incremental area extends in a ring completely around the tank. The location of this ring is specified by ψ_m , the angular distance from the vertical z -axis. Each ring with area A_t is further divided into incremental areas ΔA_t of constant size over the entire tank surface. The number of individual rings to be included in each of the separate tank surfaces used in the enclosure is then readily determined once the angular size of each of the surfaces is specified.

The variable MLI thickness over any particular tank surface area is accounted for by reading in the number of nodes used at that particular location. The numerical values of a and b (the major and minor semi-axes of the spheroid formed by the surface of the MLI) are determined individually for each of the tank areas used.

$$a = X_r + \Delta S$$

$$b = Y_r + \Delta S$$

where ΔS is the thickness of the MLI and X_r and Y_r are the uninsulated tank dimensions. Thus for any particular surface area of the tank, the existing MLI thickness over that particular area is considered to exist over the entire tank surface.

Both the tank and the payload are symmetrical about their respective z -axes. Because of this symmetry and the fact that the z -axes of both coordinate systems coincide, the geometric view factor of any one element ΔA_t along a given tank ring to any given

complete payload ring is independent of position. Thus, equation (16) may be written in the following manner:

$$A_t F_{t,p} = A_t \sum_{A_p} \frac{\cos \varphi_t \cos \varphi_p \Delta A_p}{\pi R^2} \quad (19)$$

where A_t and A_p are the tank and payload ring areas, respectively. Thus, the view factor $F_{t,p}$ of any ring on the tank to any ring on the payload is the summation of the view factors to all the incremental areas making up the payload ring.

To simplify the geometry, the typical element ΔA_t on any given tank ring, selected to view all elements ΔA_p on any given payload ring, is located in the yz plane. In this plane, the equation of the MLI surface is

$$\frac{y^2}{a^2} + \frac{z^2}{b^2} = 1 \quad (20)$$

The following geometric relations are then valid:

$$\left. \begin{aligned} R_t &= ab \sqrt{\frac{1}{b^2 \sin^2 \psi_m + a^2 \cos^2 \psi_m}} \\ y_t &= R_t \sin \psi_m \\ z_t &= R_t \cos \psi_m \\ \Delta h &= b - z_t \end{aligned} \right\} \quad (21)$$

For each value of ψ_m used, the entire payload will be divided into incremental areas ΔA_p . Thus, R_p will be a function of the payload ring being considered, and γ_n will be a function of the location of ΔA_p . The following relations can be seen from figure 6:

$$\left. \begin{aligned} x_p &= R_p \cos \gamma_n \\ y_p &= R_p \sin \gamma_n \\ \Delta A_p &= \frac{\pi}{N_J} \left[\left(R_p + \frac{\Delta L}{2} \right)^2 - \left(R_p - \frac{\Delta L}{2} \right)^2 \right] \end{aligned} \right\} \quad (22)$$

where N_J is determined by equation (17). Differentiating equation (20) gives the slope at any point on the curve:

$$\frac{dz}{dy} = - \frac{b^2}{a^2} \frac{y}{z} \quad (23)$$

The slope of a line normal to that point m_{N_1} can be expressed as

$$m_{N_t} = - \frac{1}{\frac{dz}{dy}} = \frac{a^2}{b^2} \frac{z}{y} = \frac{a^2 z_t}{b^2 y_t} \quad (24)$$

where z_t and y_t are the coordinates of the point shown in figure 6. The vector \vec{N}_t representing the normal from this point is

$$\vec{N}_t = \hat{j} + m_{N_t} \hat{k} \quad (25)$$

and the unit vector \hat{N}_t becomes

$$\hat{N}_t = \frac{\hat{j} + m_{N_t} \hat{k}}{\left| \sqrt{1 + m_{N_t}^2} \right|} \quad (26)$$

Since the payload surface is in the xy plane,

$$\hat{N}_p = -\hat{k} \quad (27)$$

The vector $\vec{R}_{t,p}$ from ΔA_t to ΔA_p can be expressed as

$$\vec{R}_{t,p} = (x_p - x_t) \hat{i} + (y_p - y_t) \hat{j} + (z_p - z_t) \hat{k} \quad (28)$$

Since $x_t = 0$,

$$\vec{R}_{t,p} = x_p \hat{i} + (y_p - y_t) \hat{j} + (z_p - z_t) \hat{k} \quad (29)$$

$$R = \left| \sqrt{x_p^2 + (y_p - y_t)^2 + (z_p - z_t)^2} \right| \quad (30)$$

Thus the unit vector $\hat{R}_{t,p}$ becomes

$$\hat{R}_{t,p} = \frac{x_p \hat{i} + (y_p - y_t) \hat{j} + (z_p - z_t) \hat{k}}{R} \quad (31)$$

and

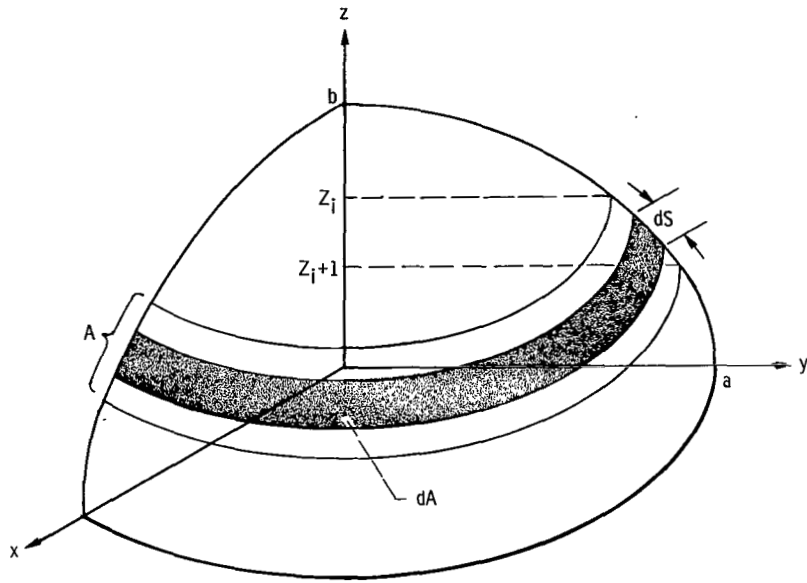
$$\hat{R}_{p,t} = -\hat{R}_{t,p} \quad (32)$$

The angles φ_t and φ_p can now be determined by forming scalar products:

$$\cos \varphi_t = \hat{N}_t \cdot \hat{R}_{t,p} = \frac{(y_p - y_t) + m_{N_t}(z_p - z_t)}{R \left| \sqrt{1 + m_{N_t}^2} \right|} \quad (33)$$

$$\cos \varphi_p = \hat{N}_p \cdot \hat{R}_{p,t} = \frac{z_p - z_t}{R}$$

The tank surface area A of any ring is determined with the equation obtained from the following derivation:



(c)

$$dA = 2\pi y \, ds$$

$$ds = \sqrt{(dy)^2 + (dz)^2}$$

$$\frac{y^2}{a^2} + \frac{z^2}{b^2} = 1$$

$$y = a \sqrt{1 - \frac{z^2}{b^2}}$$

$$dy = \frac{-az \, dz}{b^2 \sqrt{1 - \frac{z^2}{b^2}}}$$

$$\therefore dA = (2\pi) \left(a \sqrt{1 - \frac{z^2}{b^2}} \right) \left[\sqrt{\frac{a^2 z^2}{b^4 \left(1 - \frac{z^2}{b^2} \right)} + 1} \right] dz$$

$$\therefore dA = 2\pi a \left[\sqrt{1 + \left(\frac{a^2}{b^4} - \frac{1}{b^2} \right) z^2} \right] dz$$

$$\therefore A = 2\pi a \int_{z_i}^{z_{i+1}} \sqrt{1 + w^2 z^2} dz$$

where

$$w^2 = \frac{a^2}{b^4} - \frac{1}{b^2} = \frac{a^2 - b^2}{b^4}$$

Thus

$$A_p = 2\pi a \left[\frac{z}{2} \sqrt{1 + w^2 z^2} + \frac{1}{2w} \ln \left(zw + \sqrt{w^2 z^2 + 1} \right) \right]_{z_i}^{z_{i+1}} \quad (34)$$

Therefore all quantities required in equation (19) are determined.

To obtain the value of $A_m F_{m,n}$ between specific areas m and n is simply an appropriate summation of the results of equation (19):

$$A_m F_{m,n} = \sum_{\substack{\text{All tank} \\ \text{rings in the} \\ m^{\text{th}} \text{ segment}}} \sum_{\substack{\text{All payload} \\ \text{rings in the} \\ n^{\text{th}} \text{ segment}}} A_t F_{t,p} \quad (35)$$

All other values of $A_m F_{m,n}$ can now be generated using the following relations:

- (1) Since no surface "sees" itself, $F_{m,m} = 0$ for any m .
- (2) Since no two surfaces on the tank "see" each other, $F_{m,n} = 0$ for all tank surfaces m and n .
- (3) Since no two surfaces on the payload "see" each other, $F_{m,n} = 0$ for all payload surfaces m and n .
- (4) By definition,
$$\sum_{n=1}^{\text{All surfaces}} F_{m,n} = 1.$$
- (5) By reciprocity, $A_m F_{m,n} = A_n F_{n,m}$.

DESCRIPTION OF SUBROUTINES

As previously discussed, the program is divided into three phases: (1) the pre-preprocessor, which by using the input data described in appendix A of this report computes the input data needed to run a problem with CINDA-3G and generates a tape according to the formats given on pages 4.1 to 4.2 of reference 2; (2) the preprocessor, as described in reference 2; and (3) the execution phase, which actually computes the temperature distribution.

Pre-preprocessor Phase

The pre-preprocessor is composed of four subroutines which read data cards describing the geometry, compute the data required by the CINDA-3G system, and write this data onto a tape to be used in phase 2.

The subroutines in the pre-preprocessor are as follows:

Subroutine name	FORTTRAN call name	Brief description
PREPRE	Main program	Reads the input data, computes the data required by CINDA-3G
VIEWFC	VIEWF	Computes the geometric view factors for the radiation interchange used in subroutine IRRAD1
RAYOUT	RITARY	Called by PREPRE; writes arrays of numbers onto the input tape as prescribed by CINDA-3G, p. 4.10 of ref. 2
COMDAT	BLOCK COMMON	Block common subroutine

Preprocessor Phase

The preprocessor is the second phase of the operation. A list of the subroutines and a description of each is given in reference 2 (pp. 8.1 to 8.3). The only variation is that the preprocessor reads the data from the tape that was prepared by the pre-preprocessor phase instead of from cards.

Execution Phase

The actual computing to determine the temperature distribution is done in the execution phase. In this execution phase the following subroutines are used: LINKO, EXECDK, VAR1DK, VAR2DK, OUTDK, which are generated by the preprocessor phase of CINDA-3G.

LINKO is the main program. Its only function is to call the INPUT routines to read in the CINDA input data and call EXECDK.

EXECDK is called the execution block of the program. It retains control until the problem is solved. Subroutines VAR1DK, VAR2DK, and OUTDK are called by EXECDK or by other subroutines called from EXECDK.

VAR1DK, VAR2DK, and OUTDK are the subroutines generated from the VARIABLES 1 block, VARIABLES 2 block, and OUTPUT block, respectively, that are described in reference 2. The order of calculation in the execution phase of the program is described, along with a flow chart, in reference 2 (pp. 3.12 and 3.13).

Several subroutines were written by the authors and incorporated into the execution phase in the user subroutine section. These subroutines may be easily modified or re-written by the user because they must be included into the program deck as FORTRAN source cards. The subroutines are

Subroutine name	FORTAN call name
CNDCTR	GETG
OUTEND	ENDOUT
DISTR	TDIST
GRAFIC	PICTR
PUNTEM	PCHT

Subroutine CNDCTR computes the value of all internal conduction connectors G_i between two nodes i and j .

$$G_i = \frac{A_k}{l_{i,j}} \quad (36)$$

where

A area of heat flow

k thermal conductivity

l distance from the center of node i to center of node j

If the thermal conductivity varies with temperature

$$G_i = \frac{A}{\frac{l_i}{k_i} + \frac{l_j}{k_j}} \quad (37)$$

where k_i and k_j are temperature-varying thermal conductivities at nodes i and j. These conductors are computed just prior to each iteration of the network solution.

Subroutine CNDCTR as listed in this report was written to permit the use of very high thermal conductivity shields (pure aluminum as opposed to aluminized mylar) to increase the lateral thermal conductivity of some layers of the MLI. The nodes in these layers with high conductivity will be denoted as hi-k nodes. All other interior nodes with a lower conductivity will be denoted as standard nodes. It should be noted that this is conduction in the lateral direction only. The thermal conductivity for the standard nodes is determined by straight-line curve fit. Input variables CON1 and CON2 are the a and b, respectively, for the line $k = aT + b$. The data for the hi-k nodes are input in a table with variable name AKVST. The format for this table is found in appendix E. For the data used in the sample problem for both the standard nodes and the hi-k nodes see figure 8 of reference 1. The thermal conductivity for conduction in the normal direction $k_{\text{effective}}$ is a combination of conduction and radiation (see ref. 1 for details). Subroutine CNDCTR also calls subroutine IRRAD1 to obtain the net Q into each surface of the radiosity enclosure.

Subroutine OUTEND calls subroutine GRAFIC and then computes and prints out the heating rates Q of the fuel tank to MLI, QNORM, and also the net heat into the MLI on the top surface of the MLI, QTS. QNORM and QTS are printed in tabular form to show the Q in or out of each segment on the tank. Further, these values are then multiplied by 8 to obtain the Q in and out for the entire tank. The names of these output variables are QN8 and QTS8. These printouts occur each time the print switch (NPRINT) calls for an output of the temperature distribution.

Subroutine TDIST reads the initial temperature distribution from tape unit SYSUT5 which was written in the pre-preprocessor.

Subroutine GRAFIC is a special subroutine which prints out the temperature distribution pictorially. Blocks are made, simulating the nodes, and are printed to simulate the shape of the shield. Inside each block is printed a node number and the temperature of that node. A node number with a minus sign in front denotes this node is a hi-k node, as described in the section on subroutine CNDCTR. If the top of the box is made up of dollar signs (\$\$\$\$\$) instead of asterisks (*****) it denotes a surface with a high surface emissivity (see sample output listing on p. 31).

Subroutine PUNTEM punches cards with the current temperatures if either the number of iteration loops or the amount of computer time requested on the TCP card is exceeded.

Lewis Research Center,
National Aeronautics and Space Administration,
Cleveland, Ohio, December 2, 1970,
129-04.

APPENDIX A

COMPUTER PROGRAM SYMBOLS

FORTRAN name	Corresponding mathematical symbol	Units in program	Description
A	A_{norm}	ft^2	Conduction area in normal direction
AFA	$A_i F_{ij}$	ft^2	Product of i^{th} surface area and the geometric view factor between i^{th} and j^{th} surfaces
AKVST	k	$\text{Btu}/(\text{hr})(\text{ft})(^{\circ}\text{F})$	Thermal conductivity table
ARCLN	---	ft	Arc length
AREAL	A_L	ft^2	Conduction area in lateral direction
BOTLIM	---	---	Integrand of equation (34) evaluated at lower limit z_i
BTA	β	deg	Angle measured from minor axis to segment boundary on tank
C	---	---	Array of user constants to CINDA-3G
CINCON	---	---	Array of control constants to CINDA-3G
CONNAM	---	---	Array of control constant names
CON1	---	---	$\left. \begin{array}{l} \text{Constant} = a \\ \text{Constant} = b \end{array} \right\} \begin{array}{l} \text{a straight-line} \\ \text{curve fit for } k \\ \text{for lateral con-} \\ \text{duction; } k = aT + b \end{array}$
CON2	---	---	
DAMPA	---	---	Damping factor (CINDA control constant)
DAREA	A_t	ft^2	Incremental area on MLI for view factor computation

FORTTRAN name	Corresponding mathematical symbol	Units in program	Description
DELDMP	---	---	Delta to add to change damping factor
DELS	---	ft	Thickness of each shield
DMLI	ΔS	ft	Thickness of MLI at a given segment
DPTH	---	ft	Thickness (depth) of each node
EMISP	ϵ	---	Emissivity of each surface of payload
EMISS	ϵ	---	Emissivity of space
EMIST	ϵ	---	Emissivity of each surface on MLI
G	G	Btu/(hr)($^{\circ}$ F)	Conductor value for heat transfer
H	h	ft	Tank-to-payload spacing
IEXECN	---	---	Name of CINDA execution routine to be used
LCK2	---	---	Tape unit SYSCK2 CINDA input written on
LUT3	---	---	Tape unit SYSUT3 used as temporary storage for FORTRAN subroutines to be used in execution phase
LUT5	---	---	Tape unit SYSUT5 initial temperatures stored on this unit, to be read in execution phase
MAXNL	---	---	Maximum number of nodes at any segment
NDAMP	---	---	Change damping factor every NDAMP iterations
NHIK	---	---	Number of high-conductivity layers

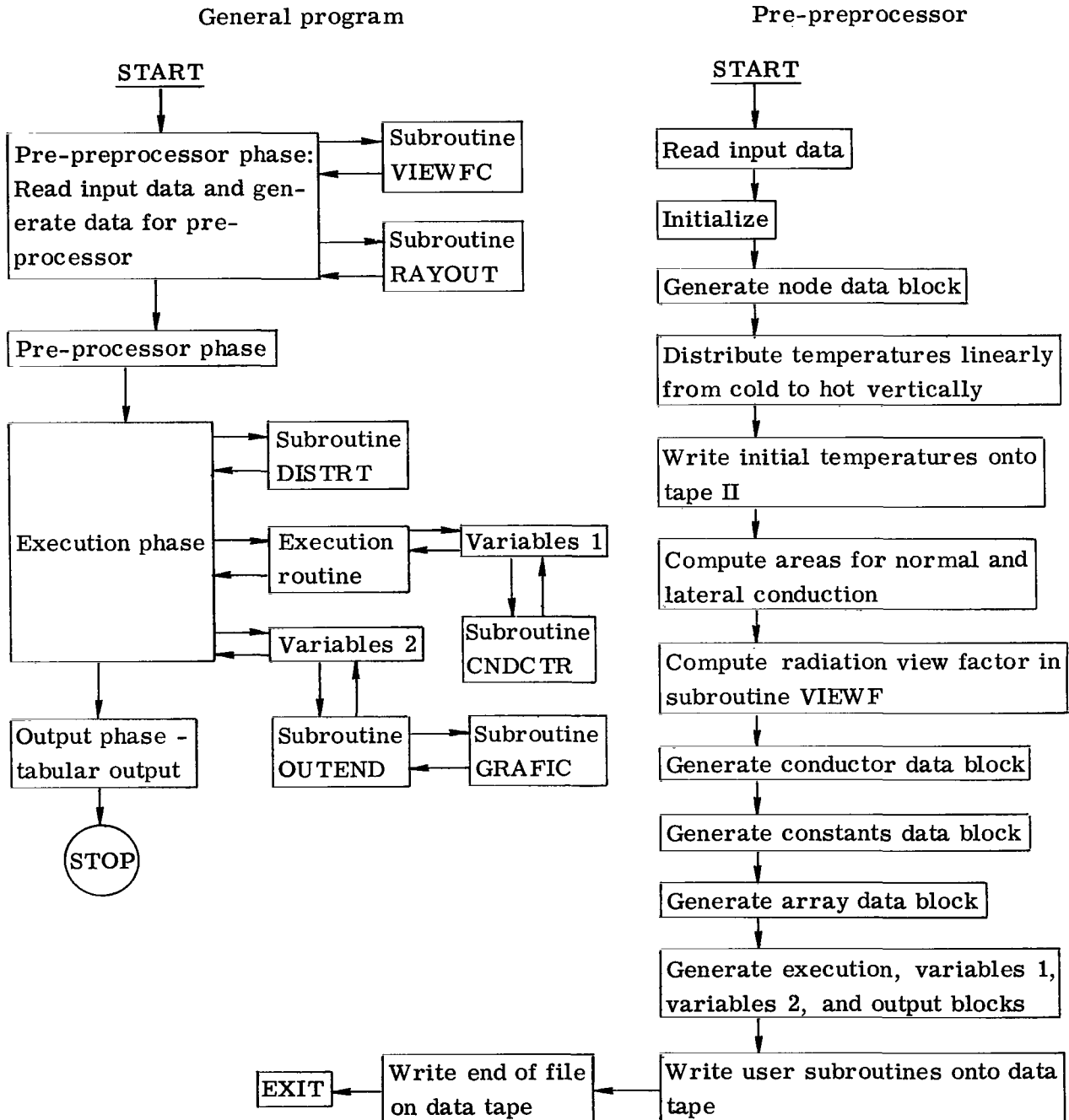
FORTTRAN name	Corresponding mathematical symbol	Units in program	Description
NIN	---	---	Tape unit, input unit
NL	---	---	Number of nodes in MLI in normal direction for each seg- ment
NNODES	---	---	Total number of nodes in con- figuration
NNPAY	---	---	Number of nodes on payload
NNSEG	---	---	Number of segments on tank
NOFA	---	---	Number of entries in view fac- tor matrix
NOUT	---	---	Tape unit, output unit
NPAY	---	---	Same as NNPAY above
NPRINT	---	---	Print temperatures every NPRINT iterations
NSEG	---	---	Same as NNSEG above
NSPL	---	---	Number of shields in each node
NSTMTS	---	---	Number of FORTRAN cards read in as user program to go into SUBROUTINES block of CINDA-3G
NSURF	---	---	Number of surfaces in radiation enclosure
NTAB	---	---	Total number of entries in K-vs-T table (AKVST)
NUMHIK	---	---	Array containing layer num- bers of high-conductivity lay- ers
PSI	ψ_m	---	Angle from top of tank to R_1
QNORM	Q	Btu/hr	Heat flow from MLI into tank

FORTTRAN name	Corresponding mathematical symbol	Units in program	Description
QTS	Q	Btu/hr	Heat flow from enclosure into top of MLI
R1	R_1	ft	Distance from tank center to incremental surface i
R1X	R_1	ft	Distance from tank center to incremental surface $i + 1$
RP	R_p	ft	Radius of payload
SLAY	---	---	Number of nodes in MLI in normal direction at each 1° increment
SPACEE	ϵ	---	Emissivity of space
TCARDS	---	---	Switch: If equal to zero, use temperatures input with input data; then distribute initial temperatures throughout configuration with subroutine TDIST. If not equal to zero, read initial temperature distribution from cards.
THETA	θ	deg	Array of angles specifying angular segments on tank
THIKN	---	---	Same as DPTH above
TPAY	T	$^\circ R$	Array temperatures of payload nodes
TSPACE	T	$^\circ R$	Temperature of space node
TSURF	T	$^\circ R$	Initial temperature on MLI surface
TWALL	T	$^\circ R$	Temperature of tank wall
UPLIM	---	---	Integrand of equation (34) evaluated at upper limit
X	X_r	ft	Major semi-axis of tank

FORTRAN name	Corresponding mathematical symbol	Units in program	Description
XM1	m_{N_1}	--	Slope
Y	Y_r	ft	Minor semi-axis of tank

APPENDIX B

FLOW DIAGRAM



APPENDIX C

DECK SETUP

The following is the deck setup to run this program at Lewis Research Center on the IBM 7094-7044 Direct Couple System using IBSYS version 13:

```
cc1          cc8      cc16
$ID          JO       USER NAME
$TCP                TIME=XX, PAGES=YY
$SETUP       10       CIN3G
$IBJOB
```

FORTTRAN IV source or binary decks of pre-preprocessor as described in this report.
(Includes subroutines PREPRE, VIEWFC, RAYOUT, and COMDAT.)

\$DATA

FORTTRAN IV source cards of user-written subroutines. For this problem these subroutines include CNDC TR, OUTEND, DISTRT, GRAFIC, and PUNTEM. Any other user-written subroutines may be added here.

ENDX

Input data as described in appendix E.

\$IBSYS

\$REWIND SYSCK2

\$SWITCH SYSIN1, SYSCK2

APPENDIX D

TAPE USAGE

Tape units must be made compatible between CINDA-3G and the computer system. A table of tape usage presently being used at Lewis Research Center only with the CINDA-3G program is included to aid in making this compatible with other systems.

SYSUNI name	FORTTRAN number in CINDA-3G	Variable name in program	Lewis system number	Function
UT3	2	LUT3	14	Copy of original problem data
UT4	3	LUT4	15	Parameter change data*
UT8	4	LUT1	3	Data number definitions
IN1	5	NIN	5	Input
OU1	6	NOUT	6	Output
UT2	8	LUT2	13	NA-NB pairs, data number definitions for parameter changes
CK1	9	-----	10	CINDA-3G master tape
CK2	10	-----	16	New master tape if updating, also used as problem recall data tape*
UT5	11	-----	7	Problem store data tape*
UT6	12	LBD3	1	Data tape (original problem and all parameter changes)
PP1(LB4)	13	-----	Calcomp	System plot tape
LB3	14	LB4P	9	Program tape (contains generated FORTRAN routines; LINKO, EXECUTN, VARBL1, VARBL2, OUTCAL)

SYSUNI name	FORTTRAN number in CINDA-3G	Variable name in program	Lewis system number	Function
UT7	15	LUT7	2	Variables 1 calls generated from node and conductor data blocks*
UT9	16	-----	4	} Internal file for reread
UT9	99	-----	4	
LB2	17	-----	8	Overlay tape

The tapes marked by an asterisk need not be assigned if the particular options are not used. The STOREP option in CINDA-3G requires assigning and saving tapes on units LB3 and UT5. The RECALL option requires assigning and mounting these two tapes onto units LB3 and CK2, respectively.

APPENDIX E

DESCRIPTION AND FORMAT OF INPUT DATA TO PRE-PREPROCESSOR

Input Data Description

```

CARD 1  FORMAT( I4, 2I3, 7F10.5)
        NSEG      NO. OF SEGMENTS      (MAXIMUM 30)
        NPAY      NO. OF SURFACES, (SEGMENTS) ON PAYLOAD      (MAXIMUM 10)
        NSPL      NO. OF SHIELDS PER LAYER
        DELS      THICKNESS OF EACH (SHIELD+SPACER)      FT.
        TWALL     TEMPERATURE OF TANKWALL      DEG.R
        TSURF     TEMPERATURE OF TOP SURFACE OF SHIELD      DEG.R
        TSPACE    TEMPERATURE OF SPACE      DEG.R
        EMISS     EMISIVITY USED IN EQUATION FOR K(EFF),
                  CONDUCTION IN NORMAL DIRECTION
        SPACEE    EMISIVITY OF SPACE
        RP        RADIUS OF PAYLOAD      FT.

CARD 2  FORMAT( 6F10.5, A6)
        TCARDS    SWITCH- TO READ INITIAL TEMPERATURES
                  IF TCARDS =0, CARDS WILL NOT BE READ. THE PROGRAM
                  USES TWALL AND TSURF AND DISTRIBUTES THE TEMPERATURES
                  BETWEEN THESE TWO VALUES AS THE INITIAL TEMPERATURE
                  DISTRIBUTION.
                  IF TCARDS .GT. 0 THE INITIAL TEMPERATURE DISTRIBUTION
                  IS READ FROM CARDS, (DEG. R). SEE CARDS 11 BELOW.
        X         LENGTH OF SEMI-AXIS OF ELIPSE, (TANKWALL),ALONG X AXIS
        Y         LENGTH OF SEMI-AXIS OF ELIPSE, (TANKWALL),ALONG Y AXIS
        H         TANK TO PAYLOAD SPACING      FT.
        CON1      CONSTANTS USED FOR STRAIGHT LINE CURVE FIT TO COMPUTE
        CON2      THERMAL CONDUCTIVITY FOR G VALUES FOR LATERAL
                  CONDUCTION OF STANDARD NODES. K=CON1*T+CON2.
        IEXECN    NAME OF EXECUTION ROUTINE      CINDSS OR CINDSL

CARD 3  FORMAT( 2I10, F10.5)
        NPRINT    DELTA PRINT, PRINT TEMP. DIST. EVERY NPRINT ITERATIONS
        NDAMP     CHANG DAMPING FACTOR EVERY NDAMP ITERATIONS
        DELDMP    DELTA TO ADD TO DAMPING FACTOR

CARD 4  FORMAT(I8,9F8.3)
        CINCON(I) CINDA CONTROL CONSTANTS, AS REQUIRED BY EXECUTION
                  ROUTINE BEING USED. CONSTANTS INPUT IN ORDER AS
                  FOLLOWS ACCORDING TO FORMAT GIVEN ABOVE,
                  NLOOP, ARLXCA, DAMPA, DRLXCA, DAMPD, TIMEO,
                  TIMEND, OUTPUT, DTIMEI, CSGFAC.

CARDS 5  NTAB, (AKVST(I),I=1,NTAB)      FORMAT(I6,12F6.1/(6X,12F6.1))
        TABLE OF TEMPERATURE VS. THERMAL CONDUCTIVITY FOR
        LATERAL CONDUCTION OF HIGH CONDUCTIVITY LAYERS.
        NTAB= TOTAL NO. OF ENTRIES IN TABLE (TEMPS AND K'S)
        DATA FORM  NTAB TEMP1      K1 TEMP2      K2 ---  TEMPN KN
        UNITS-- K BTU/HR-FT-DEG.R
                  T DEG.R

CARDS 6  NL      NUMBER OF LAYERS IN EACH SEGMENT FORMAT ( NI2)

```

CARDS 11 NNODES IF INITIAL TEMPS READ FROM CARDS - NO. OF NODES
T(I) INITIAL TEMPERATURES, DEG. R (18,9F8.1/10F8.1)

APPENDIX F

INPUT DATA FOR SAMPLE PROBLEM

```

SHIELDING STUDY CONFIGURATION NO. 24
10 5 5 .0016667 37.0 295.0 0.0 0.24 1.0 5.0
    4.571 3.233 0.8175 .000047 .0045 CINDSS
    125 2000 0.1
    9999 .0001 0.1
104 37. .8 40. .873 45. .913 50. .970 55. 1.010 60. 1.045
    62. 1.055 64. 1.065 66. 1.0875 68. 1.105 70. 1.112 72. 1.114
    74. 1.116 75. 1.117 76. 1.116 78. 1.114 80. 1.112 82. 1.105
    84. 1.090 86. 1.085 88. 1.072 90. 1.062 95. 1.040 100. 1.012
    105. .985 110. .955 115. .925 120. .900 125. .880 130. .857
    135. .837 140. .819 145. .800 150. .785 155. .770 160. .757
    165. .742 170. .730 175. .720 180. .711 185. .700 190. .695
    195. .687 200. .683 205. .675 210. .672 215. .668 220. .665
    225. .662 230. .660 235. .658 240. .655
242220201717151311 8
2715 9 9 6 6 6 4 4 4
    .11 .11 .11 .11 .11
    520.0 520.0 520.0 520.0 520.0
    .024 .024 .024 .024 .024 .024 .900 .900
    .900 .900
4 8111315
  
```

OUTPUT FOR SAMPLE PROBLEM

SHIELDING STUDY CONFIGURATION NO. 24

```

*****
*
* PAYLOAD NODES
* NODE NOS      179      180      181      182      183
*
* TEMPS=      520.00  520.00  520.00  520.00  520.00
* EMISIV=      0.1100  0.1100  0.1100  0.1100  0.1100
*****
  
```

```

*****
*
* SPACE
* NODE NO.  184
*
* TEMP=      0.
* EMISIV 1.0000
*****
  
```

ANGLE OF EACH
SEGMENT(DEG.)

27.0 15.0 9.0 9.0 6.0 6.0 6.0 4.0 4.0 4.0

EMISIVITY OF
EACH SEGMENT

0.0240 0.0240 0.0240 0.0240 0.0240 0.0240 0.9000 0.9000 0.9000 0.9000

TANK TO PAYLOAD SPACING= 0.8175 FT.

LAYER
NO.

```

*****
24  • 25 •
    • 340.27*
    *****
23  • 24 •
    • 331.26*
    *****
22  • 23 • 48 •
    • 321.44* 317.63*
    *****
21  • 22 • 47 •
    • 310.72* 306.77*
  
```

```

*****
20  • 21 • 46 • 69 • 90 •
    • 298.88* 294.54* 286.25* 262.06*
*****
19  • 20 • 45 • 68 • 89 •
    • 285.58* 280.90* 272.16* 252.90*
*****
18  • 19 • 44 • 67 • 88 •
    • 270.27* 265.30* 256.60* 240.99*
*****
17  • 18 • 43 • 66 • 87 • 108 • 126 •
    • 252.02* 246.77* 238.48* 225.46* 215.58* 195.77*
*****
16  • 17 • 42 • 65 • 86 • 107 • 125 •
    • 228.92* 223.24* 215.80* 205.86* 197.55* 186.02*
*****
15  • -16 • -41 • -64 • -85 • -106 • -124 • -142 •
    • 195.88* 188.96* 183.10* 178.40* 173.98* 170.70* 167.44*
*****
14  • 15 • 40 • 63 • 84 • 105 • 123 • 141 •
    • 176.08* 170.70* 166.28* 162.63* 159.38* 156.82* 154.65*
*****
13  • -14 • -39 • -62 • -83 • -104 • -122 • -140 • -156 •
    • 146.57* 143.90* 141.98* 140.39* 138.87* 137.60* 136.23* 134.96*
*****
12  • 13 • 38 • 61 • 82 • 103 • 121 • 139 • 155 •
    • 131.96* 130.02* 128.59* 127.33* 126.17* 125.16* 124.16* 123.49*
*****
11  • -12 • -37 • -60 • -81 • -102 • -120 • -138 • -154 • -168 •
    • 110.36* 109.60* 108.99* 108.42* 107.84* 107.29* 106.67* 106.05* 105.40*
*****
10  • 11 • 36 • 59 • 80 • 101 • 119 • 137 • 153 • 167 •
    • 102.06* 101.46* 100.94* 100.45* 99.96* 99.51* 99.04* 98.65* 98.51*
*****
9   • 10 • 35 • 58 • 79 • 100 • 118 • 136 • 152 • 166 •
    • 91.32* 90.88* 90.47* 90.09* 89.72* 89.38* 89.04* 88.79* 88.72*
*****
8   • -9 • -34 • -57 • -78 • -99 • -117 • -135 • -151 • -165 • -177 •
    • 74.74* 74.55* 74.37* 74.18* 73.98* 73.76* 73.51* 73.20* 73.00* 72.81*
*****
7   • 8 • 33 • 56 • 77 • 98 • 116 • 134 • 150 • 164 • 176 •
    • 72.04* 71.89* 71.74* 71.60* 71.45* 71.31* 71.15* 71.08* 71.03* 70.99*
*****
6   • 7 • 32 • 55 • 76 • 97 • 115 • 133 • 149 • 163 • 175 •
    • 69.13* 69.02* 68.91* 68.80* 68.69* 68.65* 68.60* 68.57* 68.54* 68.53*
*****
5   • 6 • 31 • 54 • 75 • 96 • 114 • 132 • 148 • 162 • 174 •
    • 55.93* 65.85* 65.78* 65.71* 65.65* 65.63* 65.61* 65.60* 65.59* 65.58*
*****
4   • 5 • 30 • 53 • 74 • 95 • 113 • 131 • 147 • 161 • 173 •
    • 52.27* 62.22* 62.18* 62.14* 62.11* 62.10* 62.09* 62.08* 62.08* 62.08*
*****
3   • 4 • 29 • 52 • 73 • 94 • 112 • 130 • 146 • 160 • 172 •
    • 57.90* 57.87* 57.84* 57.83* 57.82* 57.81* 57.81* 57.80* 57.80* 57.80*
*****
2   • 3 • 28 • 51 • 72 • 93 • 111 • 129 • 145 • 159 • 171 •
    • 52.30* 52.28* 52.27* 52.26* 52.26* 52.26* 52.25* 52.25* 52.25* 52.25*
*****
1   • 2 • 27 • 50 • 71 • 92 • 110 • 128 • 144 • 158 • 170 •
    • 43.98* 43.97* 43.97* 43.97* 43.96* 43.96* 43.96* 43.96* 43.96* 43.96*
*****

```

TANKWALL	1	26	49	70	91	109	127	143	157	169
SURFACE	37.00	37.00	37.00	37.00	37.00	37.00	37.00	37.00	37.00	37.00

```

*****
*
• TANKWALL
• NODE NO.= 178
• TEMP.= 37.00
•
*****

```

SHIELDING STUDY CONFIGURATION NO. 24

NO. SEG	QTS	QNORM	QTS*8	QNORM*8
1	0.06936889	0.00018959	0.55495113	0.00151672
2	0.10318061	0.00029260	0.82544488	0.00234082
3	0.09149027	0.00025254	0.73192215	0.00202030
4	0.04330576	0.00032500	0.34644613	0.00260004
5	0.04622486	0.00023741	0.36979891	0.00189930
6	0.00980636	0.00027727	0.07845092	0.00221822
7	-0.20052147	0.00028314	-1.60417175	0.00226517
8	-0.09447652	0.00018922	-0.75581217	0.00151382
9	-0.04718843	0.00019050	-0.37750745	0.00152403
10	-0.01882567	0.00018001	-0.15060541	0.00144006
SUMMATION	0.23647E-02	0.24173E-02	0.18917E-01	0.19339E-01

FORTRAN LISTING OF AUTHOR-WRITTEN SUBROUTINES

\$IBFTC PREPRE

```

COMMON/BCD/ NBCD(60)
COMMON /TAPE/NIN,NOUT,LCK2
COMMON /RADIO/ NSEG,NPAY,NSURF,X,Y,H,RP,THICKN,PIE,SLAY(90),
1 THETAD(30),A(41),AFA(1681)
DIMENSION ID(14),BTA(31),ERAD(31),THETA(30),F(30),ITEST(50),NL(30)
DIMENSION ARCLN(30),AREAL(30),NSNOD(30),NUMHIK(30),C(36)
DIMENSION AKVST(200), EMIST(41), TPAY(10), EMISP(10)
DIMENSION ISTMT(14), T(1545), CONNAM(10), CINCON(10)
DIMENSION IFMT1(7), IFMT4(4), IFMTH(5)
DIMENSION Z1(9),Z2(9),Z3(9),Z4(9),Z5(9),Z6(9),Z7(9),Z8(9)
DIMENSION Z9(9),Z10(9),Z11(9)
EQUIVALENCE (NNSEG,C),(NNPAY,C(2)),(NSURFS,C(3)),(MNODES,C(4)),
X (MAXVL,C(5)),(NPRINT,C(6)),(NDAMP,C(7)),(NNL,C(8)),(NAREAL,C(9)),
X (NAREAN,C(10)),(NARCLN,C(11)),(NTHETA,C(12)),(NITEST,C(13)),
X (NKHIC,C(14)),(NEMISS,C(15)),(NAFA,C(16)),(NSNT,C(17)),
X (SIGMA,C(21)),(DPTH,C(22)),(DELS,C(23)),(EMISS,C(24)),
X (CON1,C(25)),(CON2,C(26)),(DELDMP,C(27)),
X (TABS,C(29)),(HIKCON,C(30)),(PSWTCH,C(31)),(RAD,C(32))
X ,(HH,C(33))
DATA IFMT1(1)/ 42H( I2/ F2.0/(10F8.5)) /
DATA IFMTH(1)/ 30H(7X,17HBCD 3THERMA ,56X ) /
DATA CONNAM(1)/60H NLOOPARLXCA DAMPADRLXCA DAMPD TIMEDTIMENDOUTPUT
10TIMEICSGFAC /
DATA ISL,IWBK,IBACK,IVARB,ISPS,ILPS,IENDX
1 /6HCINDSL,6HCNFWBK,6HCNBACK,6HCNVARB,6HL SPCS,6HL LPCS,6H ENDX /
DATA M1, ONE, ONEM, TEN20, PI, TABS, SIGMA
1 /1, 1.0, -1.0, 6H1.E+20, 3.14159265, 460.0, 0.173E-8 /
DATA
1 Z1(1)/ 54H NL, NO. OF LAYERS IN EACH SEGMENT /
2,Z2(1)/ 54H AREAL, AREA, LATERAL CONDUCTION, EACH SEGMENT (HORIZ)/
3,Z3(1)/ 54H A, AREA, NORMAL CONDUCTION, EACH SEGMENT (VERT) /
4,Z4(1)/ 54H ARCLN, ARC LENGTH, LENGTHS FOR LATERAL CONDUCTION /
5,Z5(1)/ 54H THETA (DEG.), ANGLE OF EACH SEGMENT /
6,Z6(1)/ 54H ITEST, NEGATIVE NO. IS HI-COND. LAYER, LATERAL CONDUCT/
7,Z7(1)/ 54H AKVST, K(BTU/HR.FT) VS T(DEG R) FOR HI-K LAYERS /
8,Z8(1)/ 54H EMIST, EMISSIVITY OF SHIELD, RADIATION. /
9,Z9 (1)/54H AF, AREA*VIEWFACTOR FOR RADIOSITY, FOR EACH SEGMENT /
A,Z10(1)/54H TABLE OF SURFACE NODE NUMBERS, SURFACE EACH SEGMENT /
PIE=PI
PIO4= PI/4.
NIN= 5
NOUT= 6
LUT3=2
LCK2=10
LUT5= 11
REWIND LCK2
REWIND LUT3
REWIND LUT5
DO 12 I=1,10
12 CINCON(I)=0.
C
C WRITE EXECUTE, ID, IJOB CARDS, THEN ALL CINDA3G PREPROCESSOR

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C	CARDS ONTO TAPE SYSCK2 (9)	53
C		54
	WRITE(LCK2,2000)	55
C		56
C		57
C	READ PRE-PREPROCESSOR DATA AND GENERATE CINDA DATA	58
C		59
	I=1	60
	1 READ(NIN,2018) ISTMT	61
	WRITE(LUT3) ISTMT	62
	IF(ISTMT(2) .EQ. IENDX) GO TO 7	63
	I= I+1	64
	GO TO 1	65
	7 NSTMTS= I	66
	REWIND LUT3	67
	READ(VIN,1000) ID	68
C		69
C	INPUT DATA DESCRIPTION	70
C	CARD 1 FORMAT(14, 2I3, 7F10.5)	71
C	NSEG NO. OF SEGMENTS (MAXIMUM 30)	72
C	NPAY NO. OF SURFACES, (SEGMENTS) ON PAYLOAD (MAXIMUM 10)	73
C	NSPL NO. OF SHIELDS PER LAYER	74
C	DELS THICKNESS OF EACH (SHIELD+SPACER) FT.	75
C	TWALL TEMPERATURE OF TANKWALL DEG.R	76
C	TSURF TEMPERATURE OF TOP SURFACE OF SHIELD DEG.R	77
C	TSPACE TEMPERATURE OF SPACE DEG.R	78
C	EMISS EMISIVITY USED IN EQUATION FOR K(EFF),	79
C	CONDUCTION IN NORMAL DIRECTION	80
C	SPACEE EMISIVITY OF SPACE	81
C	RP RADIUS OF PAYLOAD FT.	82
C		83
C	CARD 2 FORMAT(6F10.5, A6)	84
C	TCARDS SWITCH- TO READ INITIAL TEMPERATURES	85
C	IF TCARDS =0, CARDS WILL NOT BE READ. THE PROGRAM	86
C	USES TWALL AND TSURF AND DISTRIBUTES THE TEMPERATURES	87
C	BETWEEN THESE TWO VALUES AS THE INITIAL TEMPERATURE	88
C	DISTRIBUTION.	89
C	IF TCARDS .GT. 0 THE INITIAL TEMPERATURE DISTRIBUTION	90
C	IS READ FROM CARDS, (DEG. R). SEE CARDS 11 BELOW.	91
C	X LENGTH OF SEMI-AXIS OF ELIPSE, (TANKWALL),ALONG X AXIS	92
C	Y LENGTH OF SEMI-AXIS OF ELIPSE, (TANKWALL),ALONG Y AXIS	93
C	H TANK TO PAYLOAD SPACING FT.	94
C	CON1 CONSTANTS USED FOR STRAIGHT LINE CURVE FIT TO COMPUTE	95
C	CON2 THERMAL CONDUCTIVITY FOR G VALUES FOR LATERAL	96
C	CONDUCTION OF STANDARD NODES. K=CON1*T+CON2.	97
C	TEXECN NAME OF EXECUTION ROUTINE CINDSS OR CINDSL	98
C	CARD 3 FORMAT(2I10, F10.5)	99
C	NPRINT DELTA PRINT, PRINT TEMP. DIST. EVERY NPRINT ITERATIONS	100
C	NDAMP CHANG DAMPING FACTOR EVERY NDAMP ITERATIONS	101
C	DELDMP DELTA TO ADD TO DAMPING FACTOR	102
C		103
C	CARD 4 FORMAT(I8,9F8.3)	104
C	CINCON(I) CINDA CONTROL CONSTANTS, AS REQUIRED BY EXECUTION	105
C	ROUTINE BEING USED. CONSTANTS INPUT IN ORDER AS	106
C	FOLLOWS ACCORDING TO FORMAT GIVEN ABOVE,	107
C	NLOOP, ARLXCA, DAMPA, DRLXCA, DAMPD, TIMEO,	108
C	TIMEND, OUTPUT, DTIMEI, CSGFAC.	109
C		110
C	CARDS 5 NTAB, (AKVST(I),I=1,NTAB) FORMAT(I6,12F6.1/(6X,12F6.1))	111
C	TABLE OF TEMPERATURE VS. THERMAL CONDUCTIVITY FOR	112
C	LATERAL CONDUCTION OF HIGH CONDUCTIVITY LAYERS.	113
C	NTAB= TOTAL NO. OF ENTRIES IN TABLE (TEMPS AND K'S)	114

C	DATA FORM	NTAB TEMP1	K1 TEMP2	K2 ---	TEMPN KN	115
C		UNITS--	K BTU/HR-FT-DEG.R			116
C		T	DEG.R			117
C						118
C	CARDS 6 NL	NUMBER OF LAYERS IN EACH SEGMENT FORMAT (NI2)				119
C						120
C	CARDS 7 THETAD	ANGLE OF EACH SEGMENT, IN DEGREES, IF ALL SEGMENTS				121
C		ARE EQUAL INPUT ONLY THE FIRST. FORMAT (N I2)				122
C		THE SUM OF THE N ANGLES MUST EQUAL 90				123
C						124
C	CARDS 8	ON TWO CARDS (10F8.5)				125
C		EMISIP(I) EMISIVITY OF EACH PAYLOAD SEGMENT (MAXIMUM 10)				126
C		TPAY(I) TEMPERATURE OF EACH PAYLOAD SEGMENT (MAXIMUM 10)				127
C						128
C	CARDS 9	EMIST EMISSIVITY OF EACH SURFACE, RADIATION (8F10.5)				129
C						130
C	CARD 10	NHIK NO. OF HIGH CONDUCTIVITY LAYERS (30I2)				131
C		NUMHIK LAYER NUMBERS WHICH ARE HI COND.				132
C						133
C	CARDS 11	NNODES IF INITIAL TEMPS READ FROM CARDS - NO. OF NODES				134
C		T(I) INITIAL TEMPERATURES, DEG. R (I8,9F8.1/10F8.1)				135
C						136
	READ(NIN,1001)	NSEG,NPAY,NSPL,DELS,TWALL,TSURF,TSPLACE,EMISS,				137
	1	SPACEE,RP,TCARDS,X,Y,H,CON1,CON2,IEXECN,NPRINT,NDAMP,				138
	2	DELDMP,CINCON				139
		DPH=DELS*FLOAT(NSPL)				140
		THIKN= DPH				141
		HH=H				142
		NSEG=NSEG				143
		NNPAY= NPAY				144
		TNODE=0.0				145
		READ(5,1003)	NTAB, (AKVST(I),I=1,NTAB)			146
		HIKCON=AKVST(NTAB)				147
		IF(NSEG.GT.30)	NSEG=30			148
		IFMT1(2)=	NBCD(NSEG)			149
		IFMT1(4)=	NBCD(NSEG)			150
		READ(NIN,IFMT1)	(NL(I),I=1,NSEG),(THETAD(I),I=1,NSEG),EMISP,TPAY			151
		READ(NIN,1004)	(EMIST(I),I=1,NSEG)			152
		READ(NIN,1002)	NHIK,(NUMHIK(I),I=1,NHIK)			153
		NSURF=	NSEG + NPAY + 1			154
		NSURFS=	NSURF			155
		NOFA=	(NSURF*(NSURF+1)/2)+2			156
		J=	NSEG+1			157
		MAXNL=	0			158
		DO 201	I=1,NSEG			159
	201	IF(NL(I)	.GT. MAXNL) MAXNL=NL(I)			160
		DO 200	I=J,NSURF			161
		M=	I-J+1			162
	200	EMIST(I)=	EMISP(M)			163
		EMIST(NSURF)=	SPACEE			164
		DO 2	I=1,50			165
		2	ITEST(I)= I			166
		IF(NHIK	.LE. 0) GO TO 4			167
		DO 3	I=1,NHIK			168
		M=	NUMHIK(I)			169
		3	ITEST(M)= -ITEST(M)			170
		4	CONTINUE			171
		IFMTH(4)=	ISPS			172
		IF(IEXECN	.EQ. ISL .OR. IEXECN .EQ. IWBK .OR. IEXECN .EQ. IBACK			173
		1	.OR. IEXECN .EQ. IVARB) IFMTH(4)=ILPS			174
		IF(THETAD(2)	.GT. 0.) GO TO 5			175
		DO 6	I=2,NSEG			176
		6	THETAD(I)= THETAD(1)			177

5	BTA(1)= 0.	178
	DO 9 I=2,NSEG	179
9	BTA(I)= BTA(I-1) + THETAD(I-1)	180
	BTA(NSEG+1)=90.0	181
	WRITE(LCK2,IFMTH)	182
	WRITE(LCK2,2001) ID	183
	NSEGP1= NSEG+1	184
7001	NNL= 1	185
7002	NAREAL= NSEG+2	186
7003	NAREAN= NAREAL+NSEGP1	187
7004	NARCLN=NAREAN+NSURF+1	188
7005	NTHETA= NARCLN+NSEGP1	189
7006	NITEST=NTHETA+NSEGP1	190
7007	NKHIC= NITEST+51	191
7008	NEMISS= NKHIC+NTAB+1	192
7009	NAFA=NEMISS+NSURF+1	193
7010	NSNT=NAFA+NOFA+1	194
C		195
C	GENERATE NODE DATA	196
C	NODE NO. FOR SPACE IS NNODES	197
C	NODE NO. FOR FIRST PAYLOAD NODE IS (NNODES-NPAY)	198
C	NODE NO. FOR TANKWALL IS (NNODES-NPAY-1)	199
C		200
C	SHIELD NODES	201
C		202
	WRITE(LCK2,2032)	203
101	NNODES=0	204
C		205
C	GENERATE INTERIOR NODES	206
C		207
	DO 10 I=1,NSEG	208
10	NNODES= NNODES + NL(I)	209
	NINSN=NNODES	210
C		211
C	ADD NO. OF SURFACE NODES TO NNODES, SURF NODES ONLY ALONG TANKWALL	212
C		213
	NNODES=NNODES+NSEG	214
	TEMP= TNODE	215
	WRITE(LCK2,2003)M1 ,NNODES,M1 ,TEMP,ONE,ONE,ONE,ONEM	216
C		217
C	TANKWALL NODE	218
C		219
	NNODES= -NNODES-1	220
	TEMP= TWALL	221
	WRITE(LCK2,2004) NNODES,TEMP,ONE	222
C		223
C	PAYLOAD NODES (BOUNDARY NODES)	224
C		225
	DO 105 I=1,NPAY	226
	NNODES=NNODES-1	227
	TEMP=TPAY(I)	228
	WRITE(LCK2,2004) NNODES,TEMP,ONE	229
105	CONTINUE	230
C		231
C	NODE FOR SPACE (BOUNDARY NODE)	232
C		233
	NNODES = NNODES-1	234
	TEMP= TSPACE	235
	WRITE(LCK2,2004) NNODES,TEMP,ONE	236
104	WRITE(LCK2,2007)	237
	NNODES= IABS(NNODES)	238
	IF(TCARDS .EQ. 0.) GO TO 115	239

READ(NIN,1005) NNSPCH,(T(I),I=1,NNSPCH)	240
GO TO 110	241
115 CONTINUE	242
N=0	243
IF(TSJRF) 207,207,208	244
C	245
C CONSTANT INITIAL TEMPS	246
C	247
207 TS=ABS(TSURF)	248
DELT=0.0	249
GO TO 205	250
C	251
C DISTRIBUTE TEMPS BETWEEN TWALL AND TSURF	252
C	253
208 DELT=(TSURF-TWALL)/FLOAT(MAXNL)	254
TS=TWALL	255
205 DO210 I=1,NSEG	256
NLAY=NL(I)+1	257
N=N+1	258
T(N)=TS	259
DO211 J=2,NLAY	260
N=N+1	261
T(N)=T(N-1) +DELT	262
211 CONTINUE	263
210 CONTINUE	264
DO 212 I=1,N	265
212 T(I)=T(I)-TABS	266
110 T(NNODES)=TSPACE -TABS	267
M=NNODES-NPAY-1	268
DO 213 I=1,NPAY	269
J=M+I	270
213 T(J)=TPAY(I)-TABS	271
T(M)=TWALL-TABS	272
WRITE(LUT5) (T(I),I=1,NNODES)	273
C	274
C COMPUTE AREAS FOR LATERAL (HORIZ), AND NORMAL (VERT), CONDUCTORS	275
PUT AREAS INTO ARRAYS AREAL, AND AREAN AND OUTPUT IN ARRAY DATA AS	276
C ARRAY 2 AND ARRAY 3 RESPECTIVELY.	277
C ARRAY ARCLN, LENGTHS OF NODES, IS ARRAY 4.	278
C	279
80 CONTINUE	280
ASQ=X*X	281
BSQ=Y*Y	282
ASQBSQ= ASQ*BSQ	283
ERAD(1)=Y	284
K=0	285
DO 20 I=1,NSEG	286
ANG1= BTA(I)	287
ANG2= BTA(I+1)	288
THETA(I)= THETAD(I)*0.01745329	289
M= THETAD(I)	290
DLAY=NL(I)	291
DO 81 L=1,M	292
K=K+1	293
81 SLAY(K)=DLAY	294
ANG2= ANG2*0.01745329	295
SINAL= SIN(ANG2)	296
COSAL= COS(ANG2)	297
SSQ= SINAL**2	298
CSQ= COSAL**2	299
ERAD(I+1)= SQRT(ASQBSQ / (BSQ*SSQ + ASQ*CSQ))	300
DMLI= DPTH*FLOAT(NL(I))	301
R1= ERAD(I)+DMLI	302
R2= ERAD(I+1)+DMLI	303

	RAD= (R1+R2)/2.	304
	ARCLN(I)= RAD*THETA(I)	305
	SMALLR= R2* SINAL	306
	ENDW= SMALLR* PIO4	307
	AREAL(I)= ENDW * DPTH	308
20	CONTINUE	309
	CALL VIEWF	310
C		311
C	GENERATE CONDUCTOR DATA , ALL CONDUCTANCE VALUES WILL BE COMPUTED	312
C	IN VARIABLES 1 (THEREFORE 1.0 WILL BE USED	313
C	IN THIS ROUTINE FOR C.)	314
C		315
	WRITE(LCK2,2005)	316
C	NORMAL CONDUCTORS IN SHIELD	317
C		318
	NODA=1	319
	NCOND=1	320
	DO 11 I=1,NSEG	321
	NLAY=NL(I)	322
	NODB=NODA+1	323
	WRITE(LCK2,2006) NCOND,NLAY,M1,NODA,M1,NODB,M1,ONE,ONE,ONE,ONE	324
	NODA=NODA+NLAY+1	325
11	NCOND=NCOND+NLAY	326
C		327
C	LATERAL CONDUCTORS IN SHIELD	328
C		329
	NODA=2	330
	DO 15 I=2,NSEG	331
	NLAY=NL(I)	332
	NLMIP2=NL(I-1)+1	333
	NODB=NODA+NLMIP2	334
	WRITE(LCK2,2006) NCOND,NLAY,M1,NODA,M1,NODB,M1,ONE,ONE,ONE,ONE	335
	NODA=NODB	336
15	NCOND=NCOND+NLAY	337
C		338
C	CONDUCTORS FROM EDGE OF SHIELD TO TANKWALL	339
C		340
	NODA=0	341
	NODB=NNODES-NPAY-1	342
	NCOND=NCOND-1	343
144	DO 14 I=1,NSEG	344
	NODA=NODA+1	345
	NCOND=NCOND+1	346
	WRITE(LCK2,2026) NCOND,NODA,NODB,TEN20	347
14	NODA= NODA+NL(I)	348
C		349
C	COMPUTE TABLE OF SURFACE NODE NUMBERS	350
C		351
	NODA=0	352
	DO 16 I=1,NSEG	353
	NODA= NODA+NL(I)+1	354
	NSNOD(I)= NODA	355
16	CONTINUE	356
	J=NSEG+1	357
	JJ=NNODES-NPAY-J	358
	DO 162 I=J,NSURF	359
162	NSNOD(I)=JJ+I	360
	WRITE(LCK2,2007)	361
C		362
C	GENERATE CONSTANTS DATA	363
C		364
	WRITE(LCK2,2008) (I,C(I),I=1,20)	365

	WRITE(LCK2,2024) (I,C(I),I=21,28)	366
	WRITE(LCK2,2010) (I,C(I),I=29,36)	367
	WRITE(LCK2,2022) (CONNAM(I),CINCON(I),I=1,10)	368
	WRITE(LCK2,2007)	369
C		370
C	GENERATE ARRAY DATA BLOCK	371
C	TO OUTPUT ARRAY CALL SUBROUTINE RITARY(N,A,NO,NF,ZN)	372
C	WHERE N=ARRAY NUMBER	373
C	A=ARRAY TO BE PUT OUT	374
C	NO= NUMBER OF ELEMENTS IN THE ARRAY	375
C	NF= EITHER 1 OR 2 NF=1 IF ARRAY IS FLOATI	376
C	NF=2 IF ARRAY IS INTEGE	377
C	ZN=BCD ARRAY WHICH BECOMES A TITLE FOR	378
C	ARRAY N.	379
C		380
	WRITE(LCK2,2009)	381
	CALL RITARY(1,NL,NSEG,2,Z1)	382
	CALL RITARY(2,AREAL,NSEG,1,Z2)	383
	CALL RITARY(3,A,NSURF,1,Z3)	384
	CALL RITARY(4,ARCLN,NSEG,1,Z4)	385
	CALL RITARY(5,THETAD,NSEG,1,Z5)	386
	CALL RITARY(6,ITEST, 50 ,2,Z6)	387
	CALL RITARY(7,AKVST,NTAB,1,Z7)	388
	CALL RITARY(8,EMIST,NSURF,1,Z8)	389
	CALL RITARY (9,AFA,NOFA,1,Z9)	390
	CALL RITARY(10,NSNOD,NSURF,2,Z10)	391
	WRITE(LCK2,2007)	392
C		393
C	GENERATE EXECUTION BLOCK	394
C		395
	WRITE (LCK2,2012)	396
	WRITE(LCK2,2020)	397
	WRITE(LCK2,2033) IEXECN	398
	WRITE(LCK2,2007)	399
C		400
C	GENERATE VARIABLES 1 BLOCK	401
C		402
	WRITE(LCK2,2015)	403
	WRITE(LCK2,2007)	404
C		405
C	GENERATE VARIABLES 2 BLOCK	406
C		407
	WRITE(LCK2,2014)	408
	WRITE(LCK2,2031)	409
	WRITE(LCK2,2007)	410
C		411
C	GENERATE OUTPUT CALLS	412
C		413
	WRITE(LCK2,2016)	414
	WRITE(LCK2,2029)	415
	WRITE(LCK2,2028)	416
	WRITE(LCK2,2025)	417
	WRITE(LCK2,2030)	418
	WRITE(LCK2,2007)	419
C		420
C	WRITE SUPPLIED SUBROUTINES ONTO TAPE LCK2	421
C		422
	WRITE(LCK2,2017)	423
	DO 60 I=1,NSTMTS	424
	READ(LUT3) ISTMT	425
	60 WRITE(LCK2,2018) ISTMT	426
	WRITE(LCK2,2019)	427
	REWIND 2	428

C		429
C	WRITE SWITCH SYSIN1 TO SYSUT6, TO READ CINDA DATA BY CINDA	430
C		431
	END FILE LCK2	432
	WRITE(LCK2,2021)	433
	END FILE LCK2	434
	END FILE LCK2	435
	END FILE LCK2	436
	REWIND LCK2	437
	WRITE(NOUT,5000)	438
5000	FORMAT(51H END OF PREPRE PGM. NOW SWITCHTO INPUT FOR PREPRO)	439
	WRITE(6,5001) NSTMTS	440
5001	FORMAT(45H NO. OF STATEMENTS IN SUBROUTINES LOADED = I5)	441
	CALL EXIT	442
	READ(NIN,1000) ID	443
1000	FORMAT(13A6,A2)	444
1001	FORMAT(I4,2I3,7F10.5/6F10.5,A6/2I10,F10.5/I8,9F8.3)	445
1002	FORMAT(30I2)	446
1003	FORMAT(I6,12F6.1/(6X,12F6.1))	447
1004	FORMAT(8F10.5)	448
1005	FORMAT(I8,9F8.1/(10F8.1))	449
2000	FORMAT(20H\$EXECUTE IBJOB, 64X /	450
	1 34H\$ID COWGILL PREPRO, 50X/ 6H\$IBJOB ,78X /	451
	2 27H\$IEDIT SYSCK1,SCHF2 ,57X / 13H\$IBLDR PREPRO ,71X /	452
	2 13H\$IBLDR TAPDEF,71X/ 13H\$IBLDR FVIO. ,71X/	453
	3 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR GENLNK ,71X /	454
	4 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR PSEUDO ,71X /	455
	5 13H\$IBLDR PACK43 , 71X / 13H\$IBLDR ORMIN , 71X /	456
	6 27H\$ORIGIN ALPHA,SYSLB2 ,57X /	457
	7 13H\$IBLDR CODERD , 71X / 13H\$IBLDR DATARD , 71X /	458
	8 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR PRESUB ,71X /	459
	9 13H\$IBLDR CINDA4 , 71X / 13H\$IBLDR SEARCH, 71X /	460
	A 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR COPYSB, 71X /	461
	B 13H\$IBLDR LOCATE , 71X / 13H\$IBLDR FIBLDR , 71X /	462
	C 13H\$IBLDR READTP , 71X / 13H\$IBLDR CIN90 , 71X /	463
	D 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR INITAL , 71X /	464
	E 27H\$ORIGIN ALPHA,SYSLB2 ,57X / 13H\$IBLDR FINAL , 71X /	465
	F 27H\$ORIGIN ALPHA,SYSLB2 ,57X /	466
	G 13H\$IBLDR SKIP , 71X / 13H\$IBLDR SPLIT , 71X /	467
	H 5H\$DATA , 79X / 80X)	468
2001	FORMAT(7X,5HBCD 9,9A6,14X/7X,5HBCD 5,5A6,38X/7X,3HEND,70X)	469
2003	FORMAT(470
	1 7X,44GEN ,I1,1H,,I4,1H,,I1,1H,,F7.2,1H,,F3.1,1H,,F3.1,1H,,F3.1,	471
	2 1H,,F4.1,36X)	472
2004	FORMAT(11X,I5,1H,,F6.1,1H,,F4.1,52X)	473
2005	FORMAT(7X,19HBCD 3CONDUCTOR DATA ,54X)	474
2006	FORMAT(7X,4HGEN ,7(I4,1H,),3(F3.1,1H,),F3.1,19X)	475
2007	FORMAT(7X,3HEND,70X)	476
2008	FORMAT(7X,19HBCD 3CONSTANTS DATA,54X /	477
	1 (11X,4(I3,1H,,I5,1H,,),I3,1H,,I5,20X))	478
2009	FORMAT(7X,15HBCD 3ARRAY DATA,58X)	479
2010	FORMAT((11X,3(I2,1H,,F13.5,1H,,),I2,1H,,F13.5,2X))	480
2012	FORMAT(7X,14HBCD 3EXECUTION,59X/23HF DIMENSION X(3000),57X /	481
	1 15HF NDIM=3000,65X / 12HF NTH=0,68X)	482
2014	FORMAT(7X,16HBCD 3VARIABLES 2,57X)	483
2015	FORMAT(7X,16HBCD 3VARIABLES 1, 57X /15HF CALL GETG,65X)	484
2016	FORMAT(7X,17HBCD 3OUTPUT CALLS,56X)	485
2017	FORMAT(7X,16HBCD 3SUBROUTINES ,57X)	486
2018	FORMAT(13A6,A2)	487
2019	FORMAT(7X,16HBCD 3END OF DATA ,57X)	488
2020	FORMAT(11HF NN=10,69X/22HF IF(NN.GT.0)GOTO3,58X /	489
	1 11X,24HLAGRAN(RTEST,STEST,A7,7) ,45X/	490

2 11X,22HIRRADI(A3,A8,A9,STEST) ,47X /	491
2 14HF 3 CONTINUE,66X /	492
2 16HF CALL TDIST,64X)	493
2021 FORMAT(6H\$IBSYS,74X/21H\$REWIND SYSLB3,59X/	494
1 21H\$REWIND SYSUT6,59X/28H\$SWITCH SYSIN1,SYSLB3,52X/	495
2 28H\$SWITCH SYSIN1,SYSC2,52X)	496
2022 FORMAT(11X,A6,1H,,I4,3(1H,,A6,1H,,F9.6),7X /	497
1 11X,A6,1H,,F9.6,3(1H,,A6,1H,,F9.4),2X /	498
2 11X,A5,1H,,F9.6,1H,,A6,1H,,F9.6,36X)	499
2023 FORMAT(12X,3HEND,65X)	500
2024 FORMAT((11X,3(I2,1H,,1PE13.6,1H,,),I2,1H,,1PE13.6,2X))	501
2025 FORMAT(26HF WRITE(6,1000) LOOPCT,54X /	502
1 28HF1000 FORMAT(9HL LOOPCT= I6),52X)	503
2026 FORMAT(11X,3(I5,1H,,),3X,A6,42X)	504
2027 FORMAT(11X,3(I5,1H,,),E16.8,35X)	505
2028 FORMAT(11X,6HPRNTMP,63X)	506
2029 FORMAT(13HF NN=K(4),67X/	507
1 18HF DO 10 I=1,NN, 62X /	508
2 22HF 10 T(I)=T(I)+460.0 ,58X)	509
2030 FORMAT(18HF DO 11 I=1,NN,62X/	510
2 22HF 11 T(I)=T(I)-460.0 ,58X)	511
2031 FORMAT(17HF CALL ENDOUT,63X)	512
2032 FORMAT(7X,14HBCD 3NODE DATA,59X)	513
2033 FORMAT(11X,A6,63X)	514
END	515

\$IBFTC VIEWFC

SUBROUTINE VIEWF	1
C RADIATION VIEW FACTOR BETWEEN FLAT SURFACED PAYLOAD AND SPHEROIDAL	2
C TANK WITH VARYING MLI THICKNESS.	3
C INPUT REQUIRED	4
C SLAY - NO. OF NODES IN EACH 1 DEGREE SEGMENT	5
C RP - PAYLOAD RADIUS	6
C X AND Y - MAJOR AND MINOR RADII OF TANK (WITHOUT COVERING)	7
C NSEG - NO. OF SEGMENTS ON TANK	8
C NPAY - NO. OF RINGS ON PAYLOAD	9
C NSURF- TOTAL NO. OF SURFACES IN RADIATION ENCLOSURE	10
C H - TANK TO PAYLOAD SPACING	11
COMMON /RADIO/ NSEG,NPAY,NSURF,X,Y,H,RP,THIKN,PI,SLAY,THETA,A,AFA	12
COMMON /TAPE/ NIN,NOUT,LCK2	13
DIMENSION SLAY(90),A(41),AFA(1681),THETA(30)	14
DIMENSION SAREA(90),DAREA(90),SEGA(100),DF(600),F(600),R(10)	15
DIMENSION SAF(90,100),AF(41,41),RVF(41,41)	16
DATA W1,W2,W3,W4,W5,W6,EY1,EY2 /6H A,6H R,6H DAREA,	17
1 6H SEGA,6H RFV,6H AF,6H(I) ,6H(I,J) /	18
TOPI=2.*PI	19
ONED= PI/180.	20
HALFD=ONED/2.	21
RPSQ=RP*RP	22
N=10.*RP	23
PSI=-HALFD	24
DO 28 K=1,90	25
PSI=PSI+ONED	26
10 DMLI= SLAY(K)*THIKN	27
AX=X+DMLI	28
BX=Y+DMLI	29
AXSQ=AX*AX	30

BXSQ=BX*BX	31
SPSI=SIN(PSI)	32
CPSI=COS(PSI)	33
SSQ=SPSI*SPSI	34
CSQ=CPSI*CPSI	35
AXBX=AX*BX	36
R1= AXBX*SQRT(1./ (BXSQ*SSQ+AXSQ*CSQ))	37
Y1=R1*SPSI	38
Z1=R1*CPSI	39
DH=BX-Z1	40
XM1=(AXSQ*Z1)/(BXSQ*Y1)	41
WSQ=(AXSQ-BXSQ)/BXSQ/BXSQ	42
W=SQRT(WSQ)	43
HOW=0.5/W	44
SRQB=SQRT(1.+WSQ*BXSQ)	45
RJ=BX/2.*SRQB	46
S= HOW*ALOG(BX*W+SRQB)	47
UPLIM=RJ+S	48
PSIX=PSI+HALFD	49
SPX=SIN(PSIX)	50
CPX=COS(PSIX)	51
SPXSQ=SPX*SPX	52
CPXSQ=CPX*CPX	53
R1X= AXBX*SQRT(1./ (BXSQ*SPXSQ+AXSQ*CPXSQ))	54
Z1X=R1X*CPX	55
SRQZX=SQRT(WSQ*Z1X**2+1.)	56
T=Z1X/2.*SRQZX	57
U= HOW*ALOG(Z1X*W+SRQZX)	58
BOTLIM= T+U	59
SAREA(K)=TOPI*AX*(UPLIM-BOTLIM)	60
IF(K.EQ.1) GO TO 12	61
DAREA(K)=SAREA(K)-SAREA(K-1)	62
GO TO 14	63
12 DAREA(K)=SAREA(K)	64
14 DO 28 I=1,N	65
RING=I	66
RHO=.1*(RING-.5)	67
SIXRNG=6.*RING	68
SEGA(I)=PI*((.1*RING)**2-(.1*(RING-1.))**2)/SIXRNG	69
NSGT=5*I	70
GAMA=0.	71
DO 24 J=1,NSGT	72
IF(J.EQ.1) GO TO 16	73
GAMA=GAMA+(TOPI/SIXRNG)	74
16 X2=RHO*COS(GAMA)	75
Y2=RHO*SIN(GAMA)	76
XA= X2	77
YB= Y2-Y1	78
ZC= H-DMLI+DH	79
RV=SQRT(XA**2+YB**2+ZC**2)	80
SM= SQRT(1.+XM1**2)	81
COSP1= (YB+XM1*ZC)/(RV*SM)	82
COSP2= ZC/RV	83
IF(COSP1.LE.0.) GO TO 18	84
DF(J)=(COSP1*COSP2*SEGA(I))/(PI*RV*RV)	85
GO TO 20	86
18 DF(J)=J.	87
20 IF(J.EQ.1) GO TO 22	88
F(J)=DF(J)+F(J-1)	89
GO TO 24	90
22 F(J)=DF(J)	91
24 CONTINUE	92
SAF(K,I)=DAREA(K)*F(NSGT)	93

28	CONTINJE	94
	XNPAY=NPAY	95
	DO 30 II=1,NPAY	96
	XI=II	97
	RR=SQRT((RPSQ*XI)/XNPAY)	98
	NDELR=10.*RR	99
	XNDELR=NDELR	100
	R(II)=.1*XNDELR	101
	JJ=II+NSEG	102
	IF(II.EQ.1) GO TO 29	103
	A(JJ)= PI*(R(II)**2-R(II-1)**2)	104
	GO TO 30	105
29	A(JJ)=PI*R(II)**2	106
30	CONTINJE	107
	DO 304 KK=1,NSEG	108
	IF(KK.EQ.1) GO TO 301	109
	NDEG1=NDEG2+1	110
	NDEG=THETA(KK)	111
	NDEG2=NDEG1+NDEG-1	112
	GO TO 302	113
301	NDEG1=1	114
	NDEG2=THETA(KK)	115
302	ASUM=0.	116
	DO 303 K=NDEG1,NDEG2	117
	ASUM=ASUM+DAREA(K)	118
303	CONTINUE	119
	A(KK)=ASUM	120
304	CONTINUE	121
	A(NSURF)= 122.211	122
	DO 40 KK=1,NSEG	123
	IF(KK.EQ.1) GO TO 32	124
	NDEG1=NDEG2+1	125
	NDEG=THETA(KK)	126
	NDEG2=NDEG1+NDEG-1	127
	GO TO 34	128
32	NDEG1=1	129
	NDEG2=THETA(KK)	130
34	DO 40 II=1,NPAY	131
	IF(II.EQ.1) GO TO 36	132
	NDR1=NDR2+1	133
	NDR2=10.*R(II)	134
	GO TO 37	135
36	NDR1=1	136
	NDR2=10.*R(II)	137
37	SUM=0.	138
	DO 38 K=NDEG1,NDEG2	139
	DO 38 I=NDR1,NDR2	140
	SUM=SUM+SAF(K,I)	141
38	CONTINUE	142
	JJ=II+NSEG	143
	AF(KK,JJ)=SUM	144
40	CONTINUE	145
	DO 42 I=1,NSEG	146
	DO 42 J=1,NSEG	147
42	AF(I,J)=0.	148
	NS1=NSEG+1	149
	NS2=NSURF-1	150
	DO 44 I=NS1,NS2	151
	DO 44 J=I,NS2	152
44	AF(I,J)=0.	153
	AF(NSURF,NSURF)=0.	154
	DO 48 I=1,NSEG	155
	SUM=0	156

DO 46 K=NS1,NS2	157
46 SUM=SUM+AF(I,K)	158
48 AF(I,NSURF)=A(I)-SUM	159
DO 52 I=NS1,NS2	160
SUM=0	161
DO 50 K=1,NSEG	162
50 SUM=SUM+AF(K,I)	163
52 AF(I,NSURF)=A(I)-SUM	164
DO 60 KK=1,NSEG	165
DO 60 JJ=NS1,NSURF	166
60 RVF(KK,JJ)=AF(KK,JJ)/A(KK)	167
AFA(1)=0.0	168
AFA(2)=0.0	169
I=2	170
DO 100 KK=1,NSURF	171
DO 100 JJ=KK,NSURF	172
I= I+1	173
100 AFA(I)= AF(KK,JJ)	174
Z1=W1	175
Z2=EY1	176
WRITE(NOUT,1001) Z1,Z2,(A(I),I=1,NSURF)	177
Z1=W2	178
WRITE(NOUT,1001) Z1,Z2,(R(I),I=1,NPAY)	179
Z1=W3	180
WRITE(NOUT,1001) Z1,Z2,(DAREA(I),I=1,90)	181
Z1=W4	182
WRITE(NOUT,1001) Z1,Z2,(SEGA(I),I=1,N)	183
Z1=W5	184
Z2=EY2	185
WRITE(NOUT,1001) Z1,Z2	186
DO 200 KK=1,NSEG	187
WRITE(NOUT,1002) (RVF(KK,JJ),JJ=NS1,NSURF)	188
200 CONTINUE	189
Z1=W6	190
WRITE(NOUT,1001) Z1,Z2	191
DO 1100 KK=1,NSURF	192
WRITE(NOUT,1002) (AF(KK,JJ),JJ=KK,NSURF)	193
1100 CONTINUE	194
RETURN	195
1001 FORMAT(1HK,2A6/(1X,1P10E13.5))	196
1002 FORMAT(1X,1P10E13.5)	197
END	198

\$IBFTC RAYOUT

SUBROUTINE RITARY(NA,A,N,J,HEAD)	1
DIMENSION A(1), IFMT1(5), IFMT2(7)	2
DIMENSION HEAD(9)	3
COMMON/BCD/ NBCD(60)	4
COMMON /TAPE/ NIN,NOUT,LCK2	5
DATA IFMT1(1) /30H(12X,4 ,1H,), 4X) /	6
DATA IFMT2(1) /42H(12X, , X) /	7
DATA IFLOT1 , IFLOT2 , IFLOT3	8
1 / 6H(F12.7 , 6HF12.7, , 6H,1H,), /	9
DATA IFIX1 , IFIX2 , IBLANK	10
1 / 6H (I12 , 6H I12, , 6H /	11
DATA IE1 , IE2	12

1 / 6H(E12.5 , 6HE12.5, /	13
NSEG= N	14
JJ= J	15
IFMT2(3)= IBLANK	16
IFMT2(4)= IBLANK	17
ITEM2= IFLOT3	18
GO TO (10,11,12),JJ	19
12 IFMT1(2)=IE1	20
IFMT1(4)=IE2	21
IFMT2(5)=IE2	22
ITEM1=IE1	23
GO TO 21	24
10 IFMT1(2)= IFLOT1	25
IFMT1(4)= IFLOT2	26
IFMT2(5)= IFLOT2	27
ITEM1= IFLOT1	28
GO TO 21	29
11 IFMT1(2)= IFIX1	30
IFMT1(4)= IFIX2	31
IFMT2(5)= IFIX2	32
ITEM1= IFIX1	33
21 N1= 1	34
N2= 5	35
WRITE(LCK2,2011) NA,(HEAD(I),I=1,9)	36
31 IF (N2 .GE. NSEG) GO TO 40	37
WRITE (LCK2,IFMT1) (A(I),I=N1,N2)	38
N1= N1+5	39
N2= N2+5	40
GO TO 31	41
40 NN= NSEG-N1	42
N2= NSEG	43
IF(NN .LE. 0) GO TO 39	44
IFMT2(3)= ITEM1	45
IFMT2(4)= ITEM2	46
IFMT2(2)= NBCD(NN)	47
NBL= 56-13*NN	48
42 IFMT2(6)= NBCD(NBL)	49
WRITE(LCK2,IFMT2) (A(I),I=N1,N2)	50
WRITE (LCK2,2013)	51
RETURN	52
39 NN=1	53
IFMT2(2)=NBCD(NN)	54
NBL=56	55
GO TO 42	56
2011 FORMAT(11X,I2,3H \$,9A6,10X)	57
2013 FORMAT(12X,3HEND,65X)	58
END	59

\$IBFTC COMDAT

BLOCK DATA											1	
COMMON /BCD/ NBCD(60)											2	
DATA NBCD(1) /360H											3	
1	9	10	11	12	13	14	15	16	17	18	19	4
2	20	21	22	23	24	25	26	27	28	29	30	5
3	31	32	33	34	35	36	37	38	39	40	41	6
4	42	43	44	45	45	47	48	49	50	51	52	7
5	53	54	55	56	57	58	59	60	/			8
END											9	

\$IBFTC CNDCTR

```

SUBROUTINE GETG
COMMON /KONST/ NSEG,NPAY,NSURF,NNODES,MAXNL,NPRINT,NDAMP,NNL,
1 NAREAL,NAREAN,NARCLN,NTHETA,NITEST,NKHIC,NEMISS,NAFA,NSNT,
2 NEXTRA(3),
3 SIGMA,DPTH,DELS,EMISS,CON1,CON2,DELDMP,X,TABS,HIKCON,NPSWCH,RAD,H
COMMON /COND/ G(1)
COMMON /TEMP/ T(1)
COMMON /SOURCE/ Q(1)
COMMON /ARRAY/ A(1)
COMMON /FIXCON/ KA(1)
COMMON/QCOM/ QTS(30),QNORM(30)
DIMENSION SAREA(41),EMISIV(41),TQ(41),NTQ(1),NARY(1)
EQUIVALENCE (A,NARY), (TQ,NTQ)
EQUIVALENCE (NLOOP,KA(5)),(DAMPA,KA(9)),(LOOPCT,KA(20))
EQUIVALENCE (ARLXCC,KA(30))
DATA NTIME /1/
NPSWCH=0
IF(LOOPCT.GE.NLOOP) CALLPCHT(1)
IF(NPSWCH .GT. 0) GO TO 9998
IF(ARLXCC .LT. .01) DAMPA=DAMPA+DELDMP
IF(DAMPA .GT. 1.0) DAMPA=1.0
IF(MOD(LOOPCT,100) .NE. 0) GO TO 32
CALL TIMLEFT(TLEFT)
TLEFTM=TLEFT/3600.
WRITE(6,9999) TLEFTM,LOOPCT
IF(TLEFT .LT. 14400.0) CALL PCHT(2)
IF(NPSWCH .GT. 0) GO TO 9998
32 CONTINUE
IF(MOD(LOOPCT,NPRINT) .NE. 0) GO TO 33
35 NSP1=NSURF+1
CALL ENDOUT
WRITE(6,1001) LOOPCT,DAMPA,(TQ(I),I=1,NSP1)
33 CONTINUE
NRAD=RAD
C
C GET G FOR ALL NORMAL (VERTICAL) CONNECTORS
C
AKPART= DELS*SIGMA/((2./EMISS)-1.)
NODA= 0
NCOND= 0
N1= 1
DO 11 I=1,NSEG
M=NNL+I
NLAY= NARY(M)
MA= NAREAN+I
ADD=A(MA)/DPTH /8.
N2=N1+NLAY-1
30 DO 12 J=N1,N2
NODA= NODA+1
NODB= NODA+1
T1= T(NODA) +TABS
T2= T(NODB) +TABS
TPART= (T1+T2)*(T1*T1+T2*T2)
AK= AKPART*TPART
G(J)=ADD*AK
12 CONTINUE
NT2=NODA
41 N3=NODB-NLAY
N4=N3+1
G(N1)=G(N1)*2.
QNORM(I)=G(N1)*(T(N4)-T(N3))

```

43	CONTINUE	62
	N1= N2+1	63
40	TSURF=T(NT2)	64
11	NODA= NODA+1	65
C		66
C	COMPUTE G FOR LATERAL CONNECTORS	67
C		68
	NODA= 1	69
	NCOND= N2	70
	DO 15 I=2,NSEG	71
	M=NNL+I	72
	NLAY= NARY(M)	73
	NLM1P2=NARY(M-1)+1	74
	L=NARCLN+I	75
	EL1=A(L-1)/2.	76
	EL2=A(L)/2.	77
	LL=NAREAL+I-1	78
	AREA=A(LL)	79
	DO 13 J=1,NLAY	80
	NODA= NODA+1	81
	NODB= NODA+NLM1P2	82
	NCOND= NCOND+1	83
	T1= T(NODA) +TABS	84
	T2= T(NODB) +TABS	85
	MM=NITEST+J	86
	ITEST=NARY(MM)	87
	IF(ITEST)20,19,19	88
20	MMM=NKHIC	89
	IF(T1 .GT. 240.) GO TO 18	90
	CALL LAGRAN(T1,AK1,A(MMM),7)	91
17	IF(T2 .GT. 240.) GO TO 16	92
	CALL LAGRAN(T2,AK2,A(MMM),7)	93
	GO TO 21	94
18	AK1=HIKCON	95
	GO TO 17	96
16	AK2=HIKCON	97
	GO TO 21	98
19	AK1=CON1*T1 + CON2	99
	AK2=CON1*T2 + CON2	100
21	DEN= EL1/AK1 + EL2/AK2	101
	G(NCOND)= AREA/DEN	102
13	CONTINUE	103
15	NODA=NODA+1	104
C		105
C	COMPUTE SOURCE TERMS FOR NET Q, RADIOSITY, USING SUBR. IRRADI FOR	106
C	INTERCHANGE BETWEEN FACE OF SHIELD AND PAYLOAD	107
C		108
	GO TO (600,601),NTIME	109
600	NTIME=2	110
	J=NSURF+1	111
	M=NAREAN-1	112
	K=NEMISS-1	113
	DO 602 I=1,J	114
	MM=M+I	115
	KK=K+I	116
	SAREA(I)=A(MM)	117
	EMISIV(I)=A(KK)	118
602	CONTINUE	119
	NARY(NAFA+1)=NSURF	120
	A(NAFA+2)=SIGMA	121
	WRITE(6,1000) (SAREA(I),I=1,J)	122
	WRITE(6,1000) (EMISIV(I),I=1,J)	123

601	CONTINUE	124
	DO 500 I=1,NSURF	125
	K=NSNT+I	126
	J=NARY(K)	127
500	TQ(I+1)=T(J)	128
	NTQ(1)=NSURF	129
	CALL IRRADI(SAREA,EMISIV,A(NAFA),TQ)	130
	DO 505 I=1,NSEG	131
	K=NSNT+I	132
	J=NARY(K)	133
	Q(J)=Q(J)+TQ(I+1) /8.	134
	QTS(I)=Q(J)	135
505	CONTINUE	136
9998	RETURN	137
1000	FORMAT(1X,10G13.5)	138
1001	FORMAT(10HL LOOPCT= I6, 5X,6HDAMPA= F6.4,	139
	1 /22H NET Q FROM RADIOSITY/(1X,10G13.5))	140
9999	FORMAT(12H TIME LEFT= F15.2, 10H LOOPCT= I8)	141
	END	142

\$IBFTC OUTEND

	SUBROUTINE ENDOUT	1
	COMMON/TITLE/ HEAD(20)	2
	COMMON /KONST/ K(1)	3
	COMMON/FIXCON/ X(27),L,NP	4
	COMMON/QCOM/ QTS(30),QNORM(30)	5
	DIMENSION QTS8(30),QN8(30)	6
	NSEG=K(1)	7
	STS=0.	8
	SNO=0.	9
	CALL PICTR	10
	DO 10 I=1,NSEG	11
	QTS8(I)= QTS(I)*8.	12
	QN8(I) = QNORM(I)*8.	13
	STS=STS+QTS(I)	14
10	SNO=SNO+QNORM(I)	15
	STS8=STS*8.	16
	SNO8=SNO*8.	17
	WRITE(6,2000) (HEAD(I),I=1,20),(I,QTS(I),QNORM(I),	18
1	QTS8(I),QN8(I),I=1,NSEG)	19
	WRITE(6,2001) STS,SNO,STS8,SNO8	20
	N=K(31)	21
	L=0	22
	NP=0	23
	IF(N .EQ. 0) GO TO 4	24
	GO TO (1,2),N	25
1	WRITE(6,2003)	26
	GO TO 3	27
2	WRITE(6,2002)	28
3	WRITE(6,2004)	29
4	RETURN	30
2000	FORMAT(1H1,10X,20A6/9HL NO. SEG,8X,3HQTS,11X,5HQNORM,	31
	1 24X,5HQTS*8,9X,7HQNORM*8 //	32
	2 (18,4X,2F14.8,15X,2F14.8))	33
2001	FORMAT(12HLSUMMATION ,2G14.5,15X,2G14.5)	34
2002	FORMAT(71HLNOTE....THIS CASE STOPPED FOR TIME EXCEEDED, IT HAS NO	35
	1T YET CONVERGED.)	36
2003	FORMAT(52HL....THIS CASE STOPPED FOR ITERATION COUNT EXCEEDED.)	37
2004	FORMAT(53HKCARDS WERE PUNCHED TO RESTART FROM THIS POINT.)	38
	END	39

\$IBFTC DISTRT

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SUBROUTINE TDIST
COMMON /KONST/ K(1)
COMMON /TEMP/ T(1)
LUT5=11
REWIND LUT5
NNODES=K(4)
12 READ (LUT5) (T(I),I=1,NNODES)
RETURN
END

```

1
2
3
4
5
6
7
8
9

\$IBFTC GRAFIC

```

SUBROUTINE PICTR
COMMON/TITLE/ HEAD(20)
COMMON /TEMP/ T(1)
COMMON /ARRAY/ IA(1)
COMMON /KONST/ NSEG,NPAY,NSURF,NNODES,MAXNL,NPRINT,NDAMP,NNL,
1 NAREAL,NAREAN,NARCLN,NTHETA,NITEST,NKHIC,NEMISS,NAFA,NSNT,
2 NEXTRA(3),
3 SIGMA,DPTH,DELS,EMISS,CON1,CON2,DELDMP,X,TABS,HIKCON,PSWTCH,RAD,H
DIMENSION NODNO(15),TOUT(15), LINE(30), NBCD(50), IFMT(13)
DIMENSION NRENDN(15), NRENDT(15), IFMT1(96), A(1)
EQUIVALENCE (IA,A)
DATA ILINE,IBLANK /6H*****, 6H /
DATA ITARG /6H$$$$$/
DATA NBCD(1)/ 300H 1 2 3 4 5 6 7 8
1 9 10 11 12 13 14 15 16 17 18 19
2 20 21 22 23 24 25 26 27 28 29 30
3 31 32 33 34 35 36 37 38 39 40 41
4 42 43 44 45 46 47 48 49 50 /
DATA IFMT(1)/ 78H(2HP 8X,A1,30A4/2HP A6,A2,A1, (I6,1X,A1)/2
1HP A6,A2,A1, (F7.2,A1)) /
DATA IFMT1(1)/576H(1H1,5X,20A6/8X,10(1H*), (8H*****),2H*,
110X,17(1H*)/8X,1H*,9X, (8H ),2H *,10X,1H*,15X,1H*/8X
2,18H* PAYLOAD NODES , (8H ),2H *,10X,7H* SPACE,9X,
31H* /8X,10H* NODE NOS, 18 ,2H *,10X,10H* NODE NO.,15,2H */
48X,1H*,9X, (8H ),2H *,10X,1H*,15X,1H*/8X,10H* TEMPS=
5 , F8.2 ,2H *,10X,7H* TEMP=F8.2,2H */8X,10H* EMISIV= ,
6 F8.4 ,2H *,10X,8H* EMISIV,F7.4,2H */8X,10(1H*), (8H***
7*****),2H**,10X,17(1H*)/14HKANGLE OF EACH/14H SEGMENT(DEG.)/10X,
8 F8.1/14HKEMISIVITY OF /14H EACH SEGMENT /10X, F8.4)
9 /
DATA ISU1,ISU2,ITW1,ITW2
1 / 6HSURFAC ,6HE , 6HTANKWA ,6HLL /
DO 5 I=1,NNODES

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5	T(I)=T(I)+TABS	34
	MAXL= MAXNL+1	35
	NSPACE=NNODES	36
	NWALL=NSPACE-NPAY-1	37
	NCINIT=0	38
	NS1= 1	39
	NS2= NSEG	40
	IF(NSEG .GT. 15) NS2=15	41
8	NTH1 = NTHETA+NS1	42
	NTH2 = NTHETA+NS2	43
	NP1=NSPACE-NPAY	44
	NP2=NSPACE-1	45
	NET1=NEMISS+NS1	46
	NET2=NEMISS+NS2	47
	NEP1=NET1+NSEG	48
	NEP2=NEP1+NPAY-1	49
	NESPAC=NEMISS+NSEG+NPAY+1	50
	IFMT1(5)= NBCD(NPAY)	51
	IFMT1(13)= NBCD(NPAY)	52
	IFMT1(24)= NBCD(NPAY-1)	53
	IFMT1(35)= NBCD(NPAY)	54
	IFMT1(44)= NBCD(NPAY)	55
	IFMT1(54)= NBCD(NPAY)	56
	IFMT1(64)= NBCD(NPAY)	57
	IFMT1(73)= NBCD(NPAY)	58
	IFMT1(86)= NBCD(NSEG)	59
	IFMT1(95)= NBCD(NSEG)	60
	WRITE(6,IFMT1)HEAD,(J,J=NP1,NP2),NSPACE,(T(I),I=NP1,NP2),T(NSPACE)	61
1	, (A(I),I=NEP1,NEP2),A(NESPAC), (A(I),I=NTH1,NTH2),	62
2	(A(I),I=NET1,NET2)	63
	WRITE(6,2004) H	64
	WRITE(6,2003)	65
	DO 10 I=1,MAXL	66
	M=MAXL-I+1	67
	IM=M-1	68
9	DO 11 L=1,15	69
	LINE(L)= IBLANK	70
	LINE(L+15)= IBLANK	71
	NODNO(L)= 0	72
11	TOUT(L)= 0.0	73
	NS1P1= NS1-1	74
	NC=NCINIT	75
	N= 0	76
	ISNSW=1	77
50	IF(M .EQ. 1) GO TO 12	78
	MM1=M-1	79
52	MM=NITEST+MM1	80
	ITEST=IA(MM)	81
	IF(ITEST .LT. 0) ISNSW=-1	82
12	DO 20 J=NS1,NS2	83
	N2= 2*(J-NS1P1)	84
	N1= N2-1	85
	JJ=NNL+J	86
	JN=J-NS1+1	87
	NLAY=IA(JJ)+1	88
	IF(NLAY .LT. M) GO TO 19	89
	N= N+1	90
C		91
C	CHECK FOR TOP SURFACE TARGETING	92
C		93
26	IF(NLAY .GT. M) GO TO 21	94
C		95

C NLAY =M THIS IS A TOP SURFACE, CHECK TO SEE IF TARGETED	96
C	97
24 JJ=NEMISS+J	98
EMISIV=A(JJ)	99
IF(EMISIV .LT. 0.1) GO TO 21	100
LINE(N1)=ITARG	101
LINE(N2)=ITARG	102
GO TO 27	103
C	104
C NL(JJ) M THIS IS AN INTERIOR NODE OR TANKWALL SURFACE.	105
C	106
21 LINE(N1)= ILINE	107
LINE(N2)= ILINE	108
27 ISIGN=1	109
IF(I .LT. MAXL) GO TO 23	110
NRENDN(N)=IBLANK	111
NRENDT(N)=IBLANK	112
LEND=IBLANK	113
LLEND=ILINE	114
NAM1=ITW1	115
NAM2=ITW2	116
NAM3=ISU1	117
NAM4=ISU2	118
GO TO 18	119
23 ISIGN=ISNSW	120
LEND=ILINE	121
LLEND=ILINE	122
NAM1=NBCD(IM)	123
NAM2=IBLANK	124
NAM3=IBLANK	125
NAM4=IBLANK	126
NRENDN(N)=ILINE	127
NRENDT(N)=ILINE	128
18 NN= NC+M	129
NODNO(JN)= NN*ISIGN	130
TOUT(JN)=T(NN)	131
19 NC= NC+NLAY	132
20 CONTINUE	133
IF(N .GT. 0) GO TO 22	134
WRITE(6,2001)	135
GO TO 10	136
22 IFMT(6)= NBCD(N)	137
IFMT(11)= NBCD(N)	138
WRITE(6,IFMT)LLEND, (LINE(L),L=1,30), NAM1,NAM2,LEND,	139
1 (NODNO(L),NRENDN(L),L=1,N), NAM3,NAM4,LEND,	140
2 (TOUT(L),NRENDT(L),L=1,N)	141
10 CONTINUE	142
DO 31 I=1,3	143
31 LINE(I)=ILINE	144
WRITE(6,2002) (LINE(I),I=1,3), NWALL, T(NWALL), (LINE(I),I=1,3)	145
IF(NS2 .GE. NSEG) GO TO 40	146
NS1= NS2+1	147
NS2= NSEG	148
NCINIT=NC	149
GO TO 8	150
40 DO 41 I=1,NNODES	151
41 T(I)=T(I)-TABS	152
RETURN	153
2000 FORMAT(1H1, 5X,20A6/41X,17(1H*),10X,17(1H*)/	154
1 41X,1H*,15X,1H*,10X,1H*,15X,1H* /	155
2 41X, 9H* PAYLOAD,7X,1H*,10X,7H* SPACE,9X,1H* /	156
3 41X,10H* NODE NO.,15,2H *,10X,10H* NODE NO.,15,2H */	157

4	41X,1H*,15X,1H*,10X,1H*,15X,1H*/	158
5	41X,7H* TEMP=,F8.2,2H *,10X,7H* TEMP=,F8.2,2H */	159
6	41X,1H*,15X,1H*,10X,1H*,15X,1H*/	160
7	41X,17(1H*),10X,17(1H*) /	161
8	14HKAANGLE OF EACH / 14H SEGMENT(DEG.) / 10X,15F8.1)	162
2001	FORMAT(2HP /2HP /2HP)	163
2002	FORMAT(2HP /2HP /2HP ,41X,3A6/2HP ,41X,1H*,16X,1H*/	164
1	2HP ,41X,1H*,9H TANKWALL,7X,1H* /	165
2	2HP ,41X,1H*,10H NODE NO.=,15,2H */	166
3	2HP ,41X,1H*,7H TEMP.= F8.2,2H */	167
4	2HP ,41X,1H*,16X,1H*/2HP ,41X,3A6)	168
2003	FORMAT(7H LAYER /6H NO.)	169
2004	FORMAT(25HKTANK TO PAYLOAD SPACING= F7.4, 4H FT. /)	170
	END	171

\$IBFTC PUNTEM

	SUBROUTINE PCHT(N)	1
	COMMON /TEMP/ T(1)	2
	COMMON /FIXCON/ FC(1)	3
	COMMON/KONST/ K(1)	4
C	SET NPSWCH TO NON-ZERO TO INDICATE CARDS BEING PUNCHED	5
	K(31)=N	6
	NNODES=K(4)	7
	FC(19)=10000.	8
	WRITE(6,101)	9
	PUNCH 100, NNODES,(T(I),I=1,NNODES)	10
100	FORMAT(18,9F8.1/(10F8.1))	11
101	FORMAT(36HL TEMPERATURE CARDS BEING PUNCHED)	12
	RETURN	13
	END	14

APPENDIX H

SYMBOLS USED IN ANALYSIS

A	area, ft^2 ; m^2
ΔA	incremental area, ft^2 ; m^2
A_x	incremental area in x direction in finite difference equation, ft^2 ; m^2
A_y	incremental area in y direction in finite difference equation, ft^2 ; m^2
A_z	incremental area in z direction in finite difference equation, ft^2 ; m^2
a	major semi-axis of tank plus shield, ft; m
$A_i F_{i,j}$	product of i^{th} surface area times geometric radiation view factor between i^{th} and j^{th} surface, ft^2 ; m^2
b	minor semi-axis of tank plus shield, ft; m
C_p	specific heat, $\text{Btu}/(\text{lb})(^{\circ}\text{R})$; $\text{J}/(\text{kg})(\text{K})$
$F_{i,j}$	geometric radiation view factor - portion of total energy, either emitted or reflected diffusely from surface i , that is intercepted by surface j
G	conductor value for heat transfer, $\text{Btu}/(\text{lb})(^{\circ}\text{F})$; $\text{J}/(\text{sec})(\text{K})$
h	tank-to-payload spacing, ft; m
k	thermal conductivity, $\text{Btu}/(\text{hr})(\text{ft})(^{\circ}\text{R})$; $\text{J}/(\text{sec})(\text{m})(\text{K})$
ΔL	payload ring width, ft; m
m_{N_1}	slope of normal N_1
N	normal to center of an incremental surface
N_E	number of surfaces in radiation enclosure
N_J	number of incremental areas in j^{th} payload ring
Q	heat flow, Btu/hr ; J/sec
q	incremental heat flows, either across a plane of any segment or into (or out of) any surface segment, Btu/hr ; J/sec
\dot{q}	internal heat generation rate at each node, Btu/hr ; J/sec
R	distance between any two incremental surfaces, ft; m
R_p	payload radius, ft; m
R_1	distance from tank center to incremental surface, ft; m

R_2	distance from payload center to incremental surface, ft; m
S	source term, $\dot{q}\alpha/k$, $(\text{ft}^3)(^\circ\text{R})/\text{hr}$; $(\text{m}^3)(\text{K})/\text{sec}$
ΔS	thickness of MLI, ft; m
T	temperature, $^\circ\text{R}$; K
t	time, sec
V	volume, ft^3 ; m^3
x, y, z	coordinate system, point coordinates
x_R	major semi-axis of tank, ft; m
Δx	incremental distance in x direction
y_R	minor semi-axis of tank, ft; m
Δy	incremental distance in y direction, ft; m
Δz	incremental distance in z direction, ft; m
α	thermal diffusivity, ft^2/hr ; m^2/sec
β	angle measured from minor axis to segment boundary on tank
γ	location angle on payload
ϵ	emissivity
θ	angle on tank to specify segments
ρ	density, lb/ft^3 ; kg/m^3
φ	angle between the normal to a surface and the vector R from that surface
ψ_m	angle from top of tank to R_1

Subscripts:

i	index or counter
j	index or counter
k	index or counter
lat	lateral
m, n	reference or index
norm	normal
p	refers to payload surface increment
t	refers to tank surface increment

Notation:

\rightarrow vector

$\hat{}$ unit vector

∇^2 Laplacian operator, $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

$\hat{i}, \hat{j}, \hat{k}$ unit vectors in x, y, z directions

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3. Howell, John R.; and Siegel, Robert: Thermal Radiation Heat Transfer. Vol. II - Radiation Exchange Between Surfaces and in Enclosures. NASA SP-164, 1969.

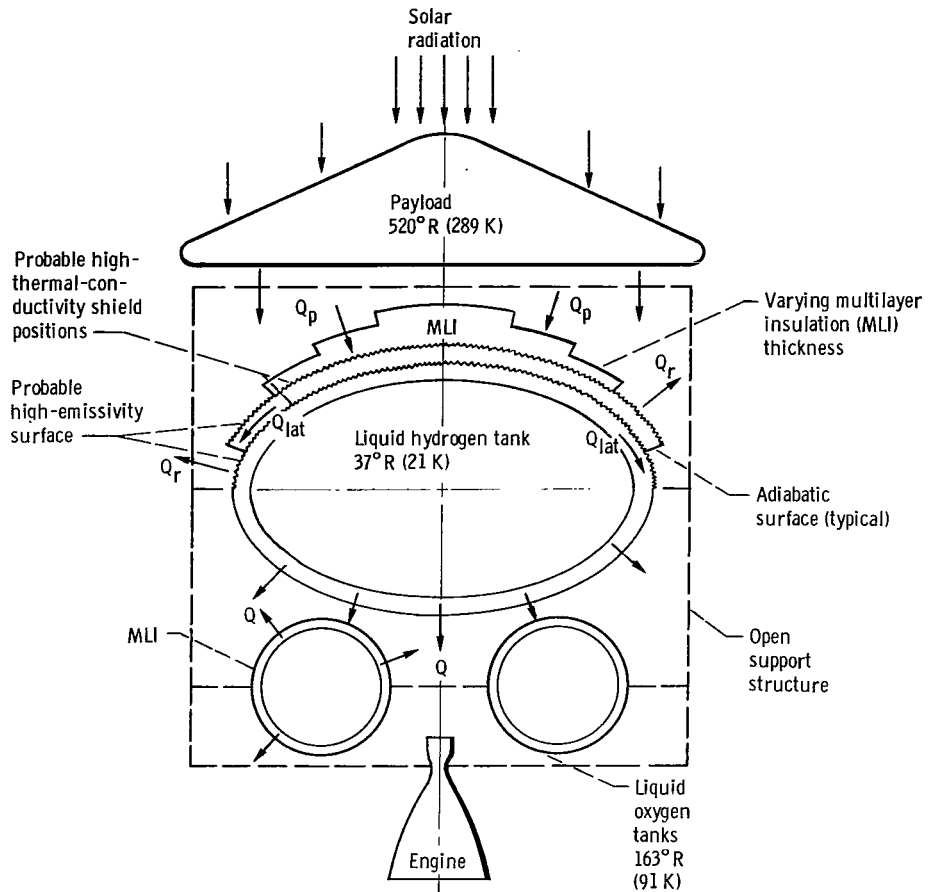


Figure 1. - Vehicle configuration.

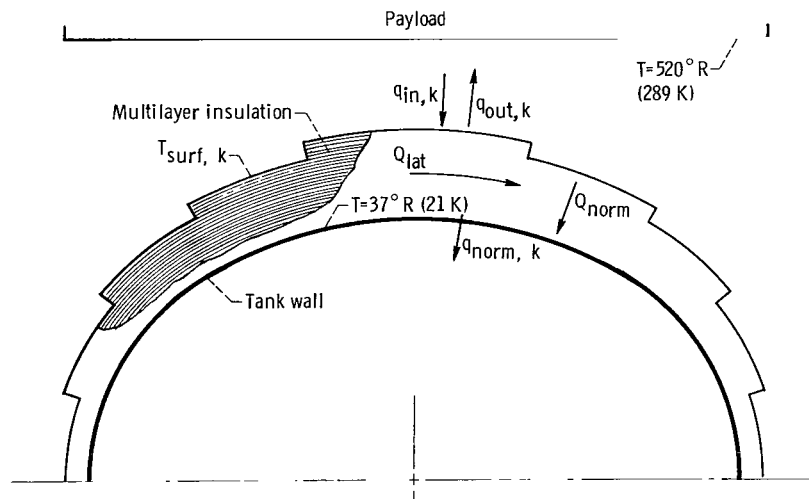


Figure 2. - Cross-sectional view of model.

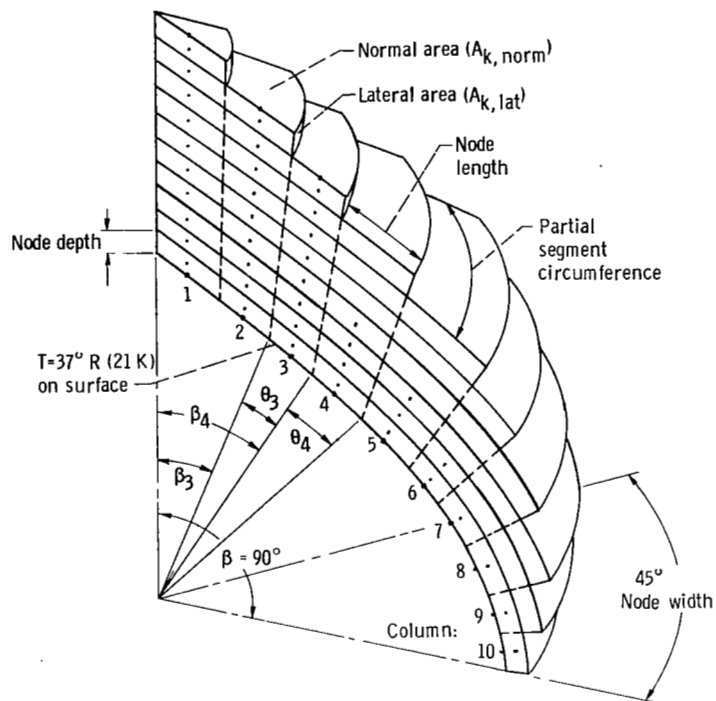


Figure 3. - 45° segment of the multilayer insulation (MLI) divided into nodes.

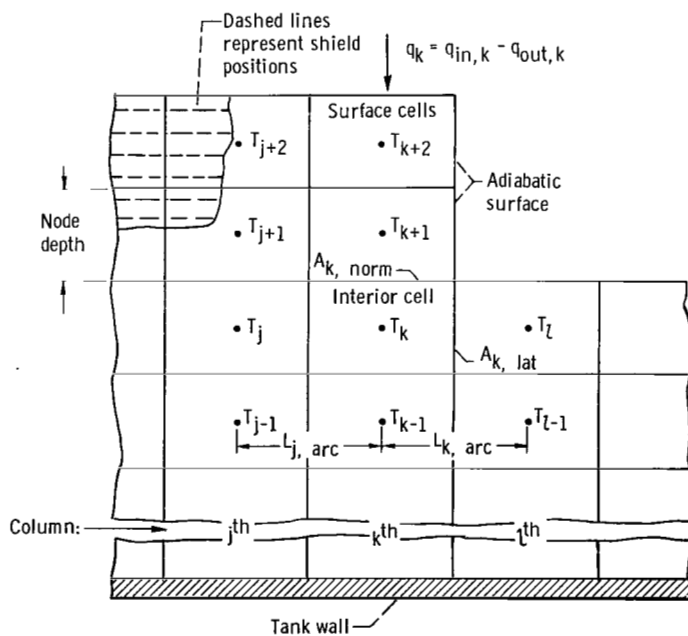


Figure 4. - Cross-sectional view of several nodes.

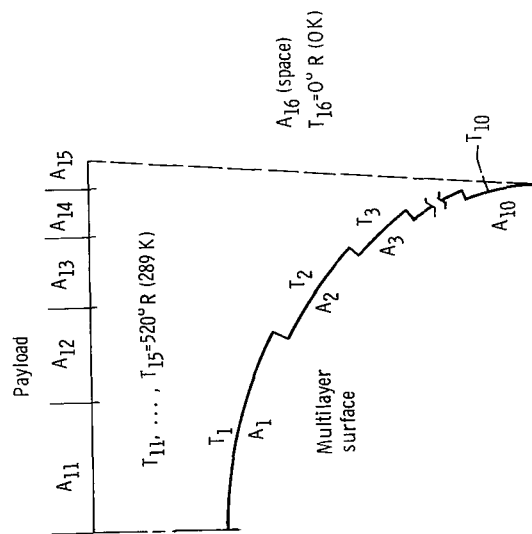


Figure 5. - Enclosure for radiation exchange.

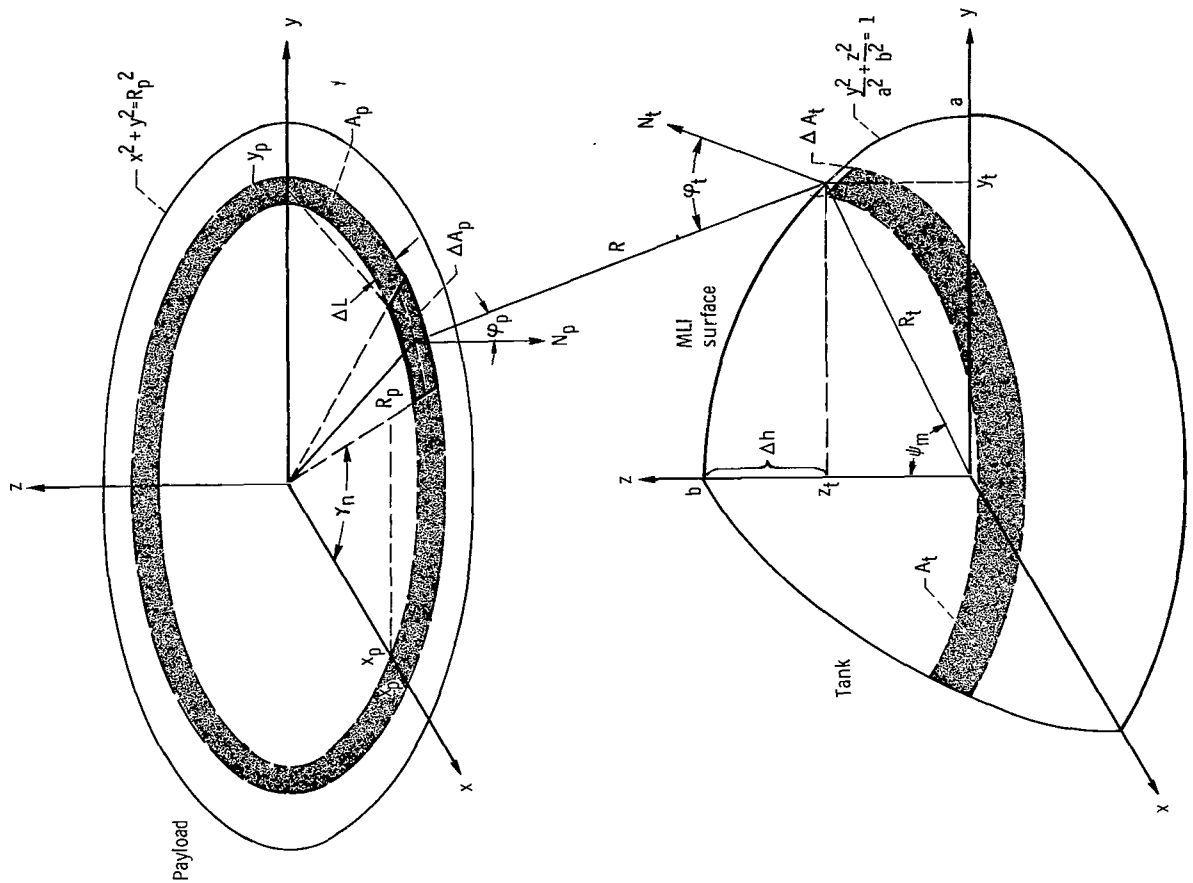


Figure 6. - Geometric configuration for determining radiation view factors between tank and payload.

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